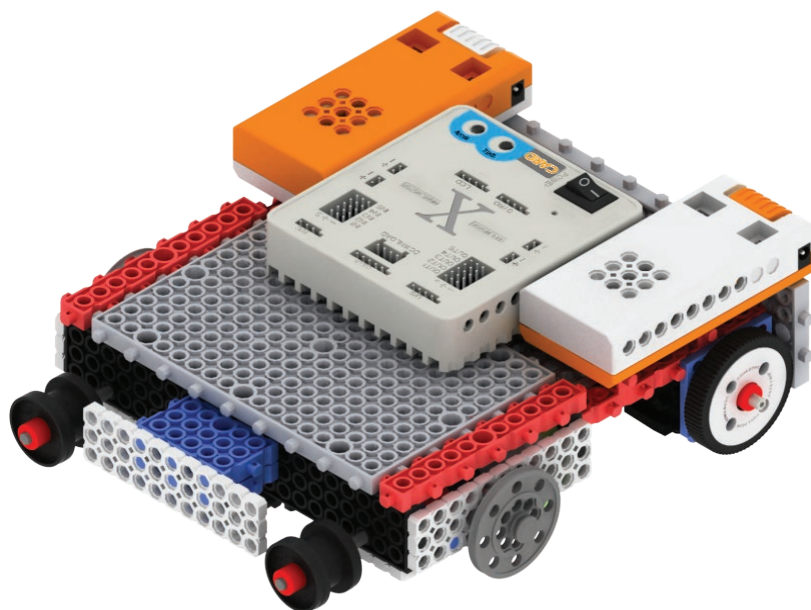
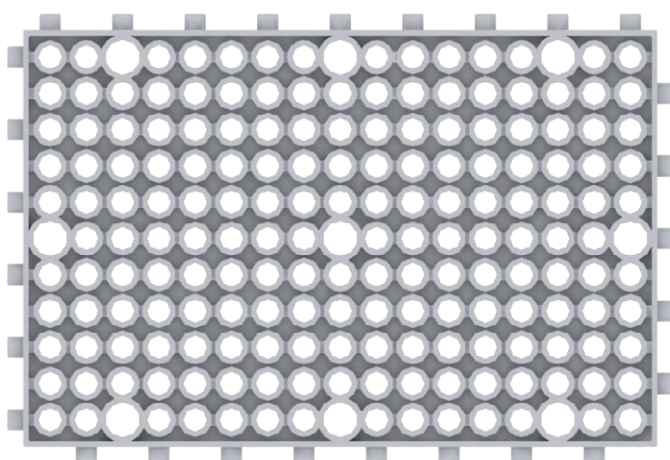




13 Mașină de tamponări



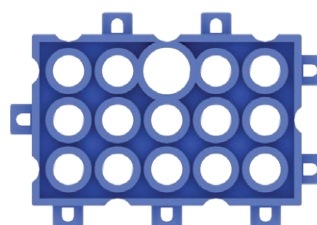
Piese



Bloc 11x17 (2)



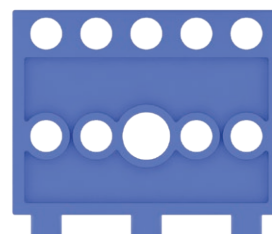
Bloc N 3x5 (2)



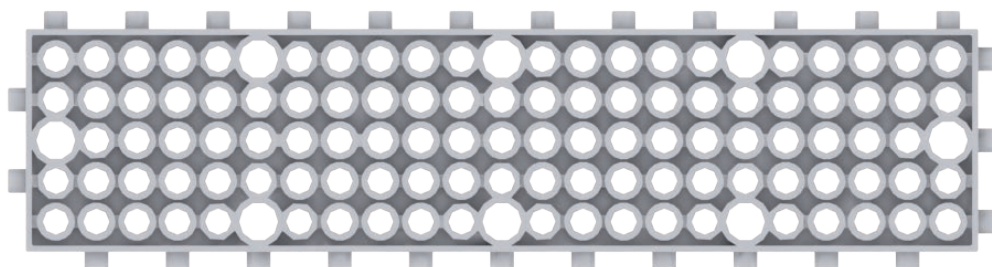
Bloc 3x5 (2)



Bloc N 3x11 (3)



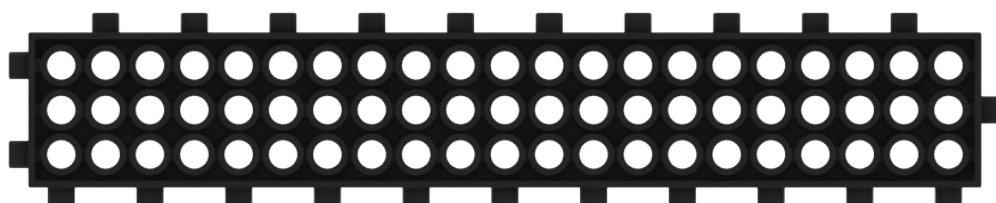
Suport de motor (2)



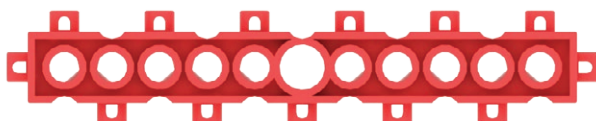
Bloc 5x23 (1)



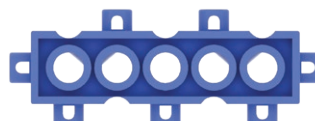
Bloc 1x21 (2)



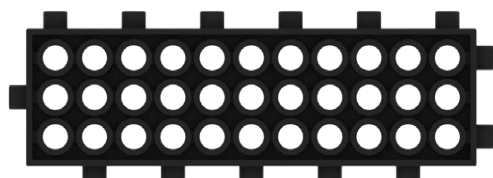
Bloc 3x21 (2)



Bloc 1x11 (4)



Bloc 1x5 (2)



Bloc 3x11 (1)



Adaptor L (2)



Roată de direcție/
Guide wheel (2)



Conector de ax (2)



Cauciuc roșu de ax/Red bush (10)



L-shaft

Ax L (2)



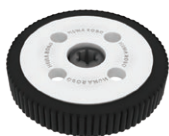
Îmbinare de axuri (2)



Piuliță (2)



Jantă/Hub 2 (2)



Roată S (2)



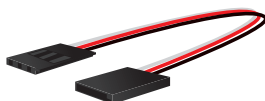
Buton cu senzor (2)



Motor 2 (2)



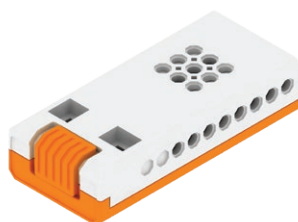
Cablu de conectare (2)



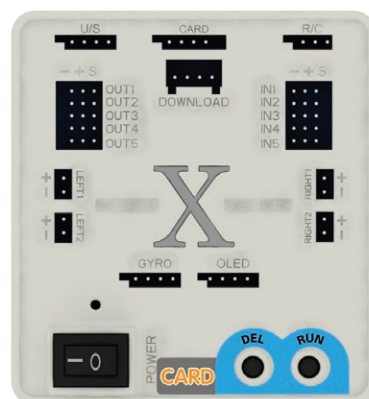
Prelungitor (2)



Acumulator 1 (1)

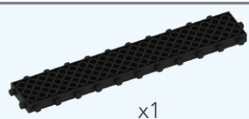
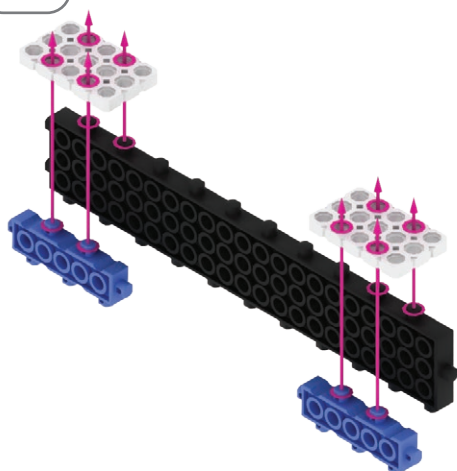


Acumulator 2 (1)

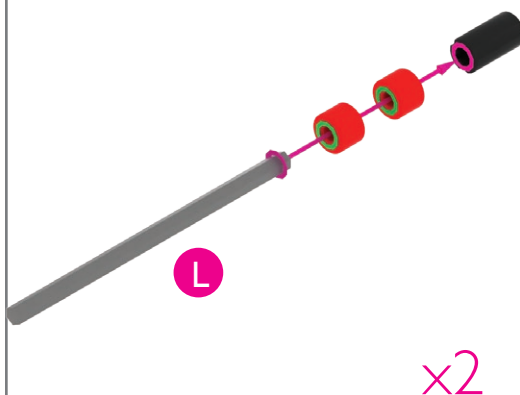


Placă de bază (1)

01



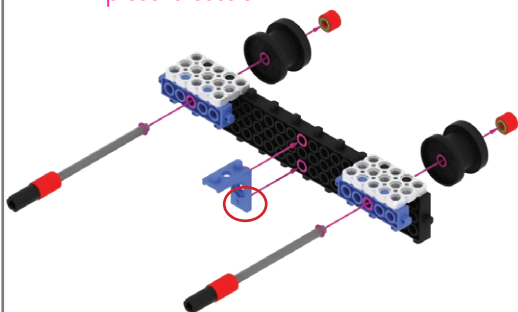
02



1:1

03

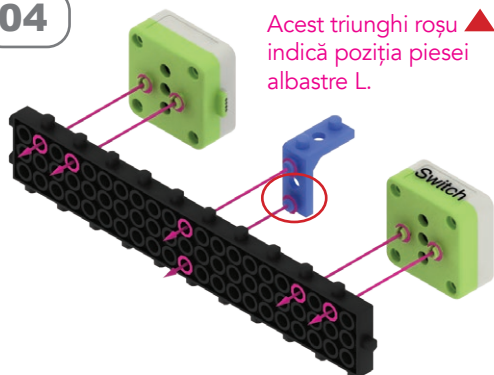
Acest triunghi roșu ▲ indică poziția piesei albastre L.



x1 x2 x2

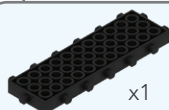
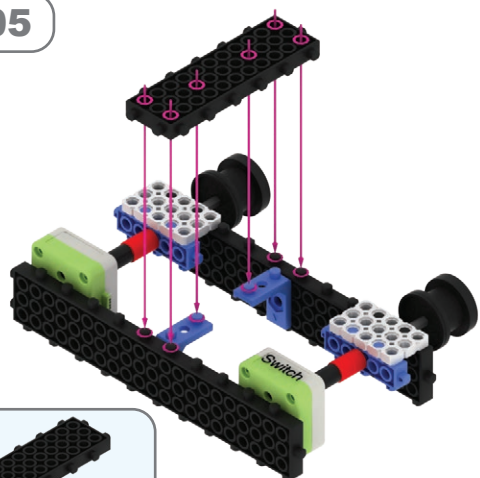
04

Acest triunghi roșu ▲ indică poziția piesei albastre L.



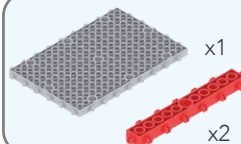
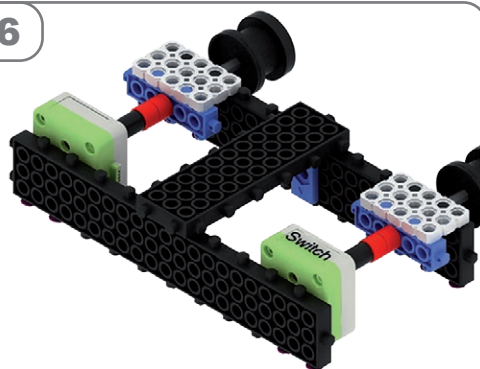
x1 x1 x2

05



x1

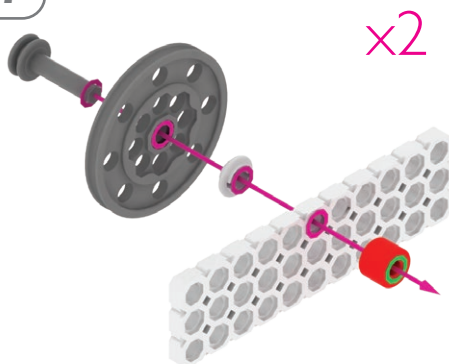
06



x1

x2

07



x2



x2

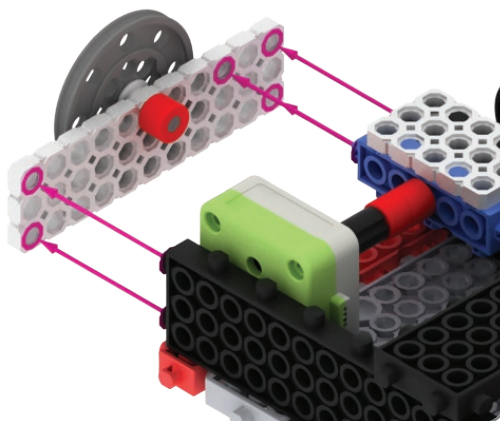
x2

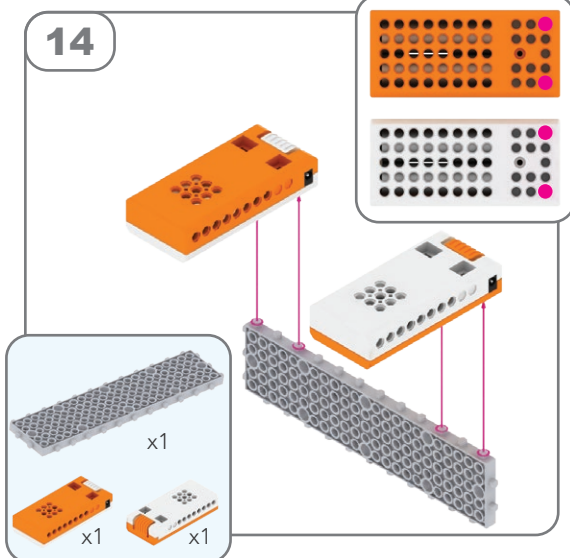
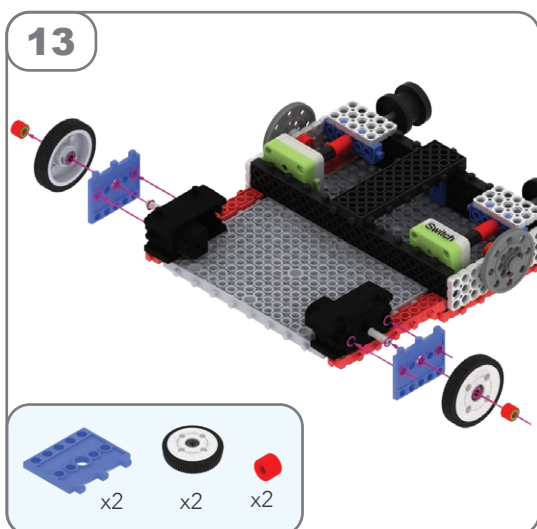
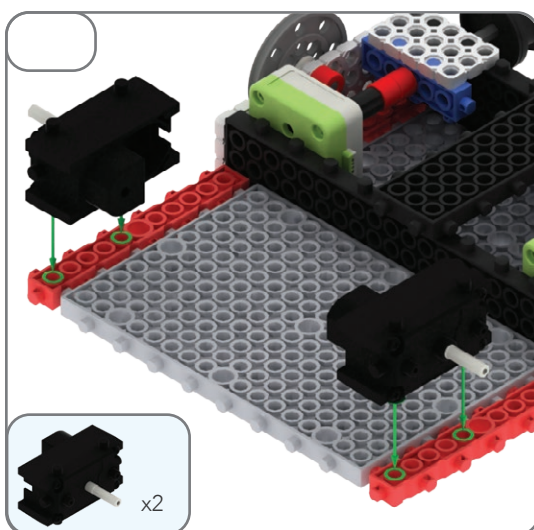
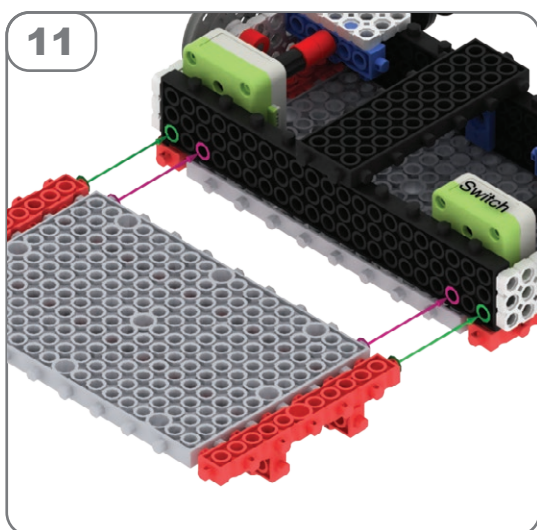
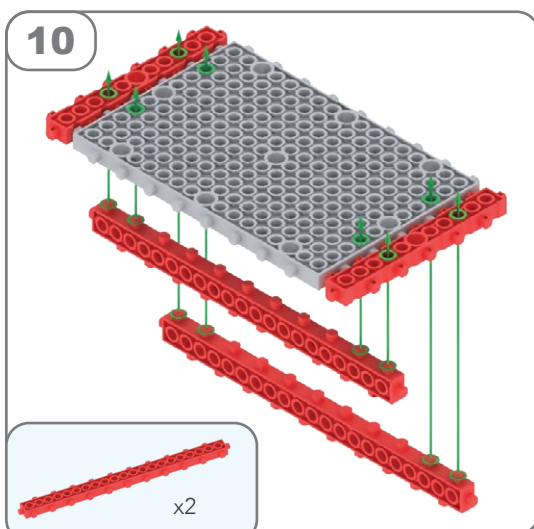
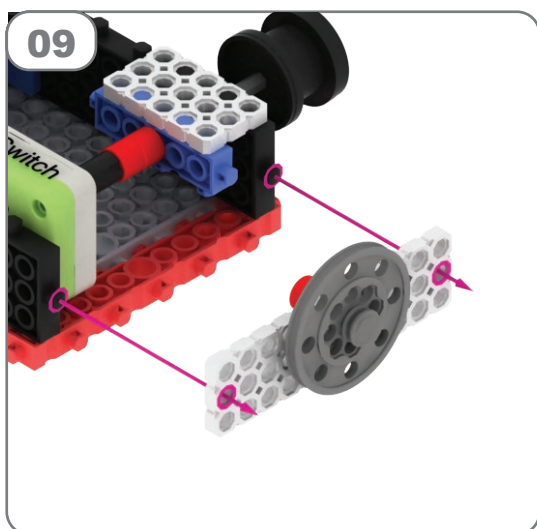
x2

x2

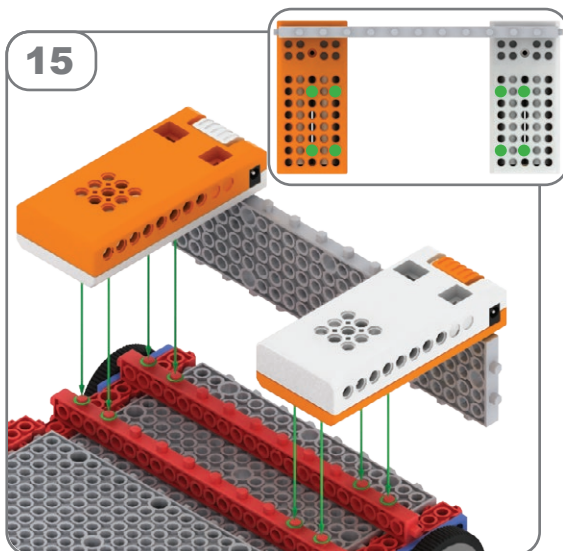
x2

08

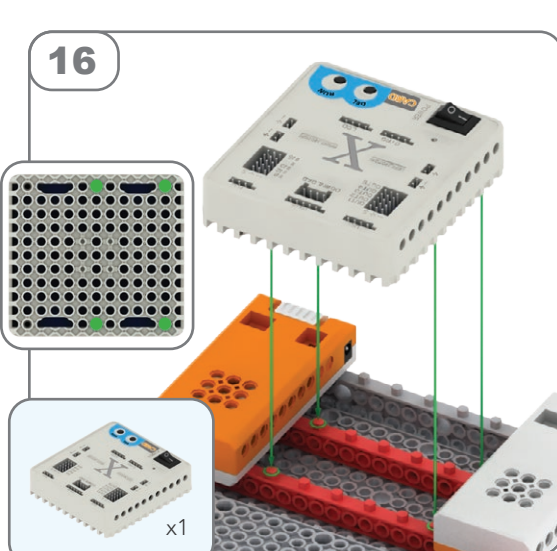




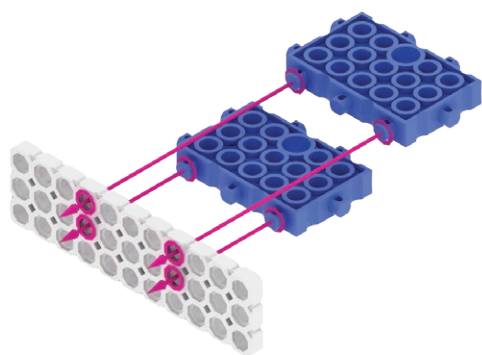
15



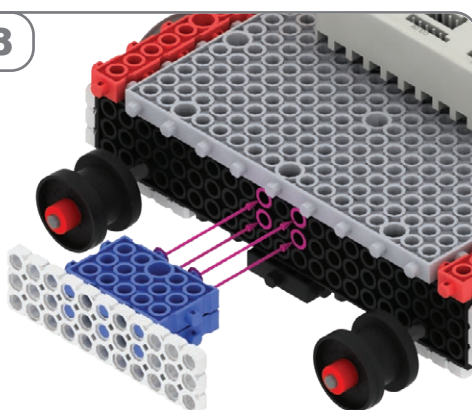
16



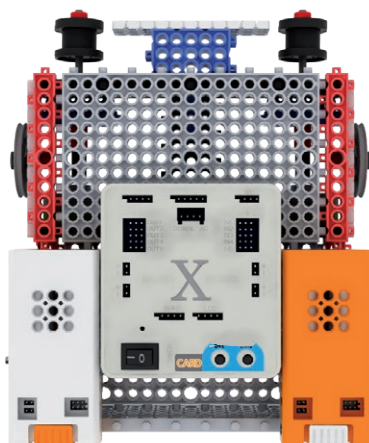
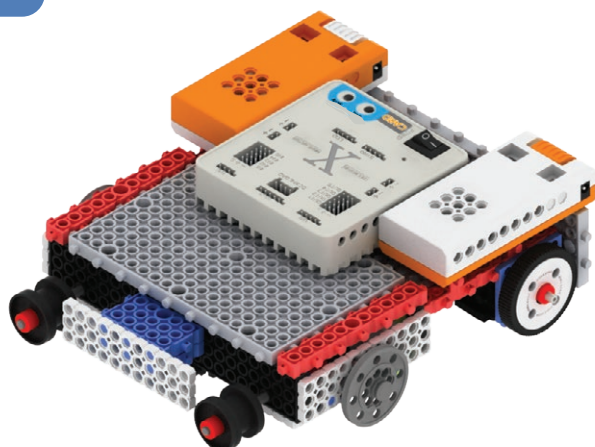
17



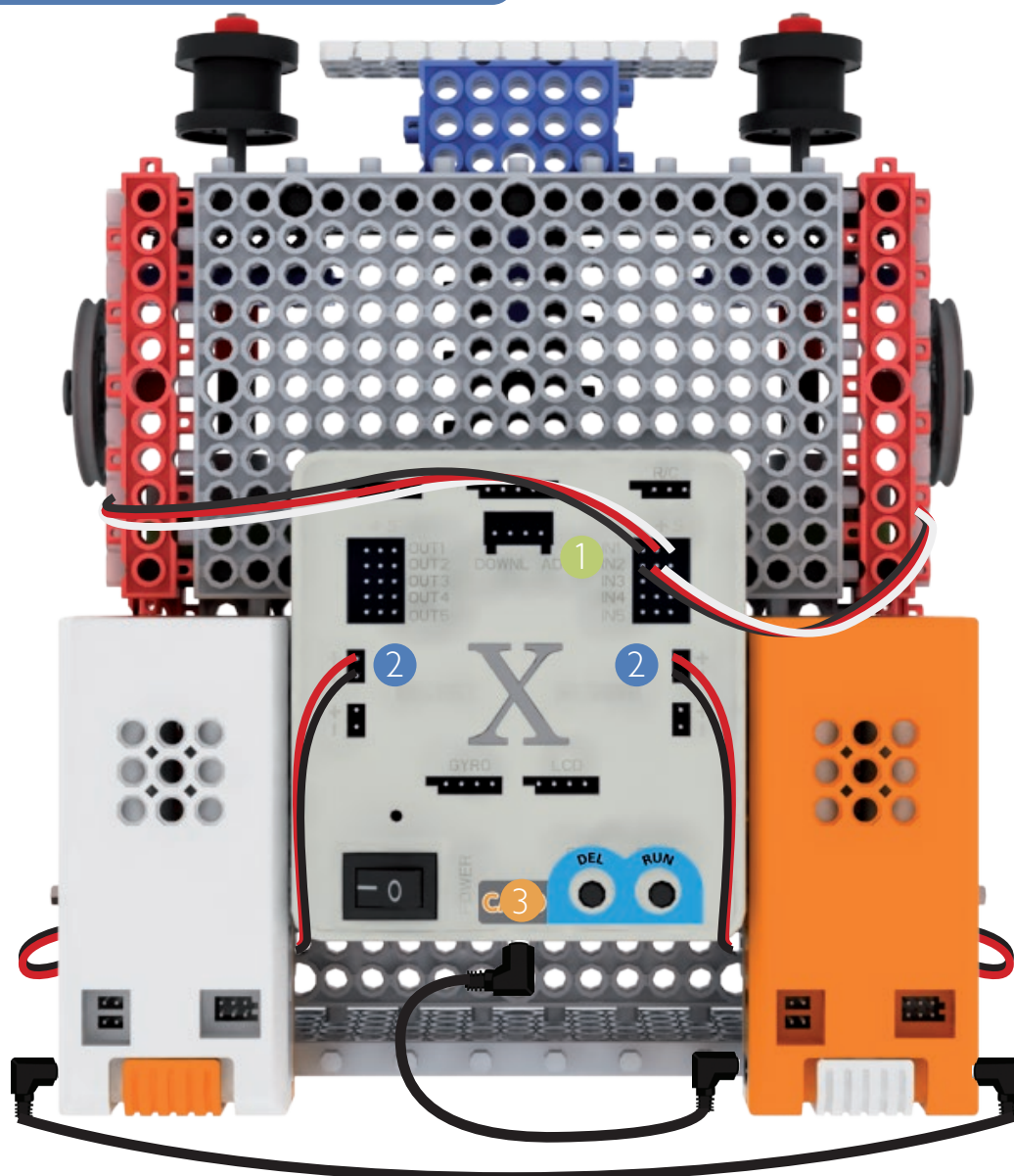
18



OK



Cum se conectează?

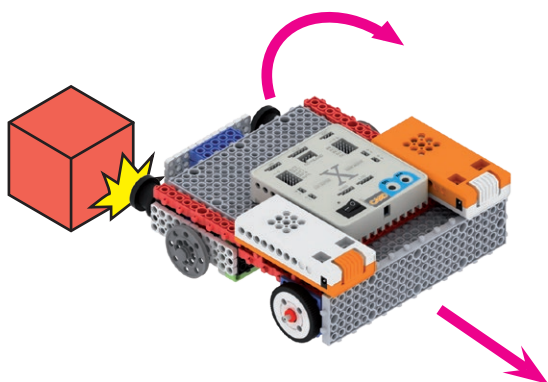


- 1 Conectează senzorul cu infraroșu din stânga la portul IN1 și pe cel din dreapta la portul IN2, așa cum ți se arată în imagine.
- 2 Conectează cele două motoare la placa de bază, așa cum ți se arată mai sus.
- 3 Conectează cei doi acumulatori la placa de bază.

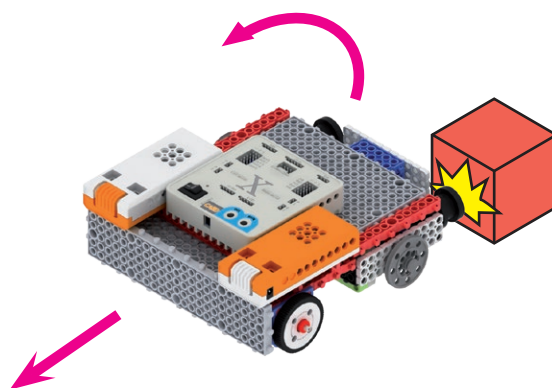
Acumulatorii vor furniza energie când sunt conectați la placă prin cablul negru, indiferent de poziția întrerupătoarelor.

În practică

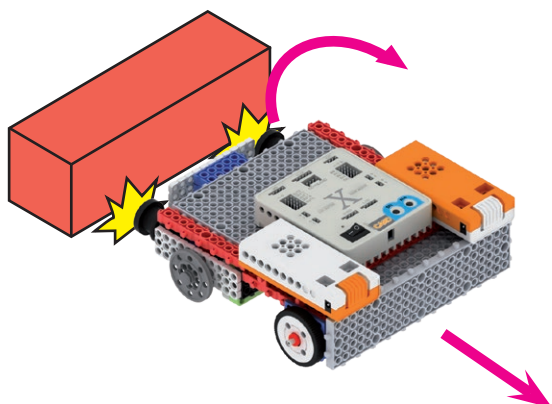
Pornește placa, apoi apasă butonul RUN și apoi DEL. X se face roșu și pâlpâie, apoi apasă RUN pentru a activa modul preprogramat 2. Robotul începe să se miște în față.



Când senzorul din stânga întâlnește un obstacol, mașina de tamponări dă cu spatele și virează la dreapta.



Când senzorul din dreapta întâlnește un obstacol, mașina de tamponări dă cu spatele și virează la stânga.



Când ambii senzori întâlnesc un obstacol, mașina de tamponări dă cu spatele și virează la dreapta.