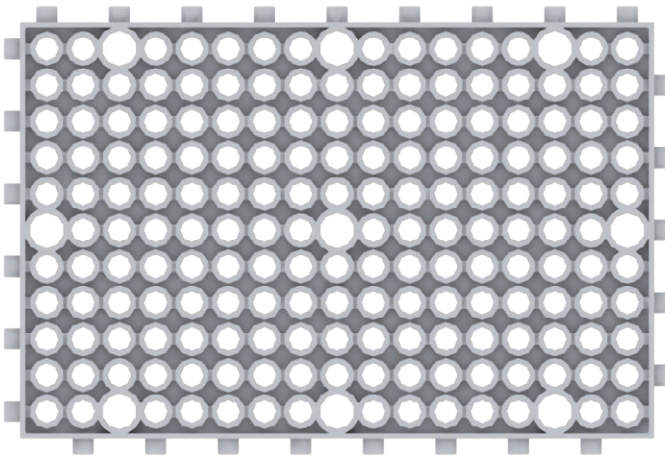




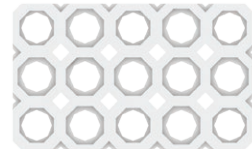
14 Câine însoțitor



Piese



Bloc 11x17 (1)



Bloc N 3x5 (1)



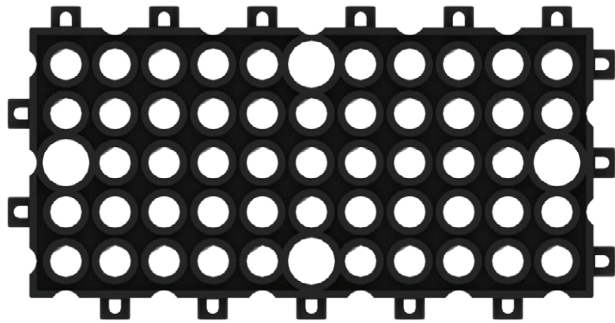
Adaptor L 2x4 (4)



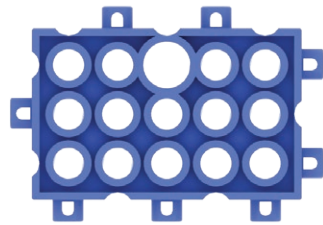
Bloc N 2x9 (2)



Bloc N 3x9 (3)



Bloc 5x11 (4)

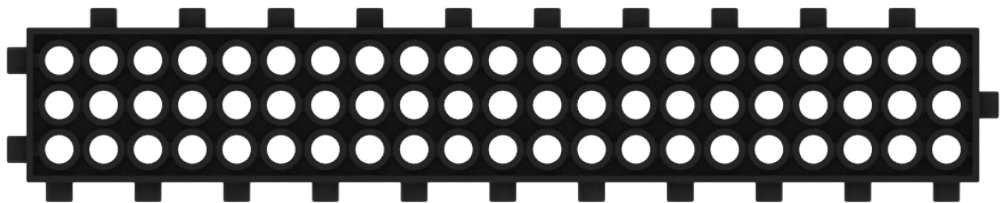


Bloc 3x5 (2)

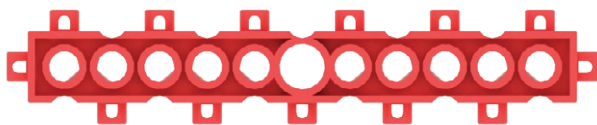


M-shaft

Ax M (2)



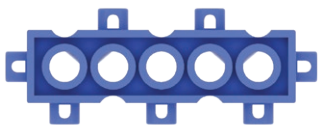
Bloc 3x21 (1)



Bloc 1x11 (2)



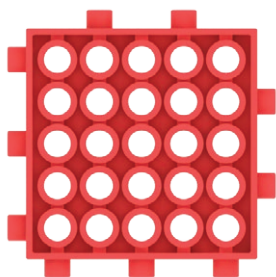
Angrenaj L (2)



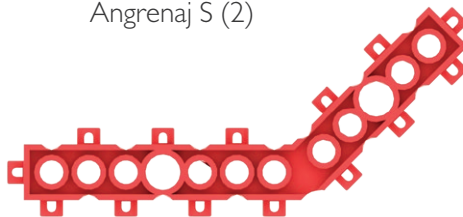
Bloc 1x5 (3)



Angrenaj S (2)



Bloc 5x5 (2)



Bloc de 135° (3)



Bloc oval (2)



Bloc de îmbinare 2 (1)



Adaptor L (2)



Roată M (2)



Cauciuc roșu de ax/
Red bush (4)



Piuliță (2)



Nit S (4)



Nit L (3)



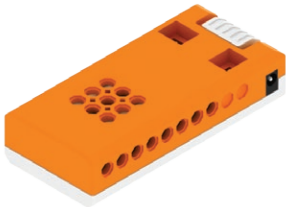
Senzor cu infraroșu (1)



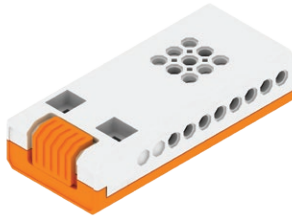
Motor 2 (2)



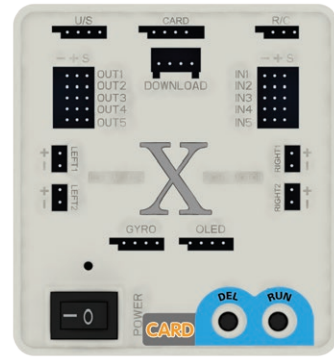
Cable de conexi3n (3)



Acumulator 1 (2)

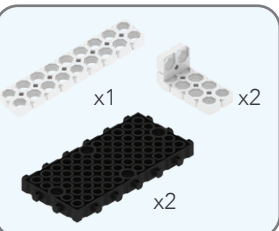
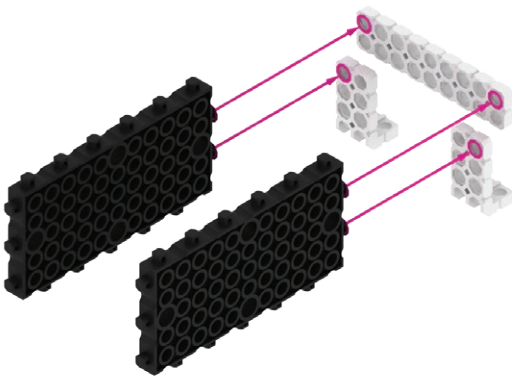


Acumulator 2 (1)

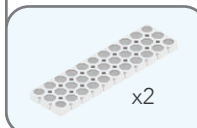
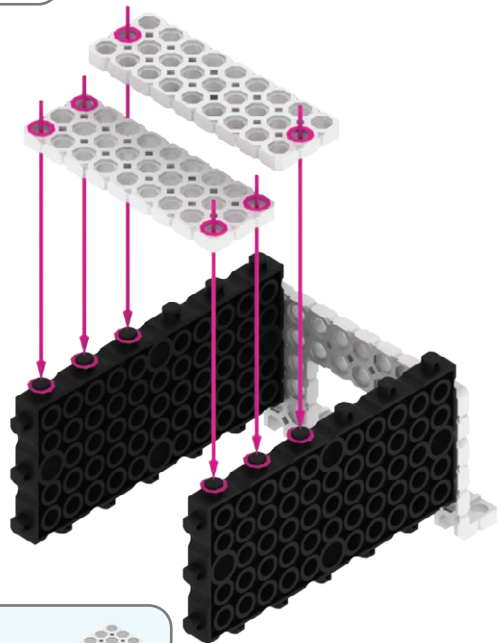


Plac3 de baz3 (1)

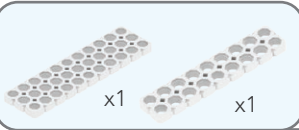
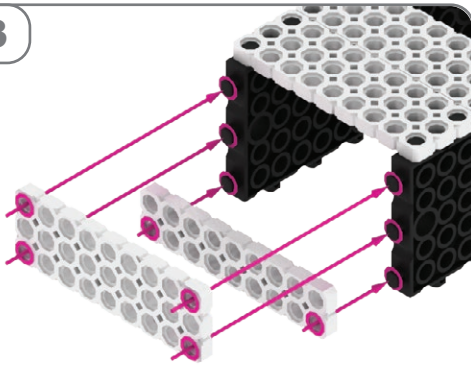
01



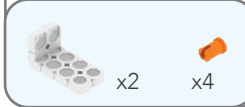
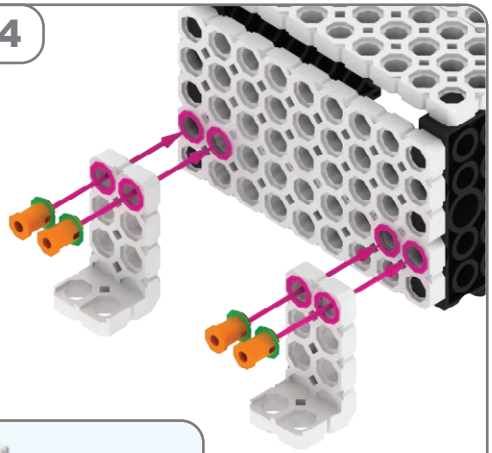
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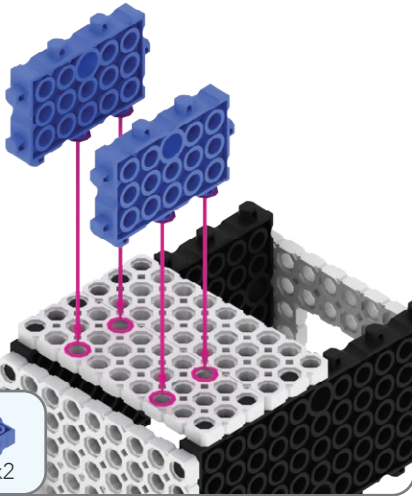
03



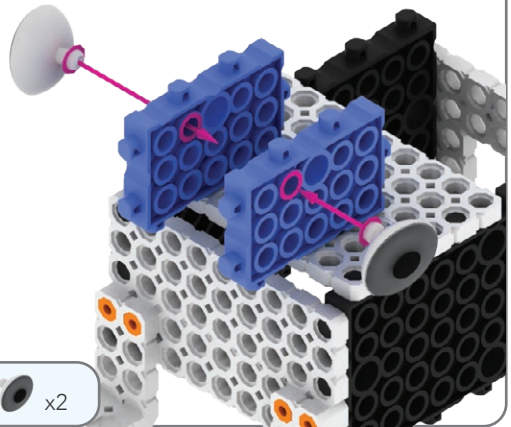
04



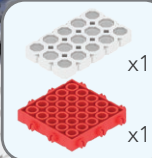
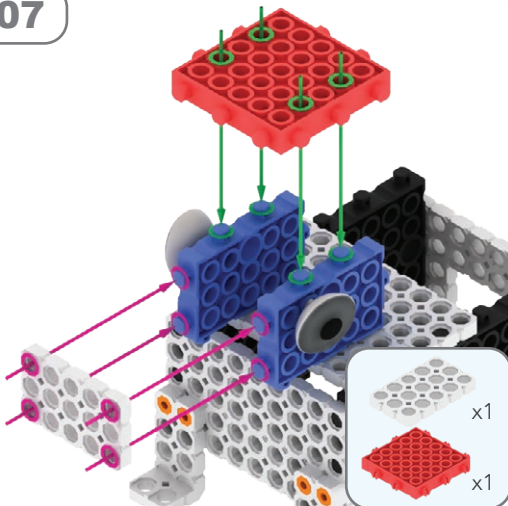
05



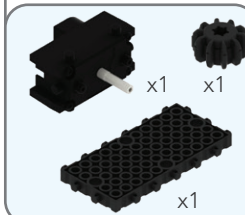
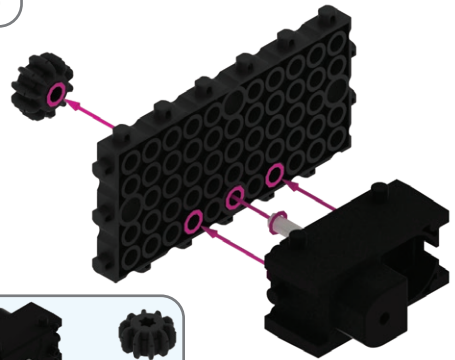
06



07



08



09

M

x1
x1
x1

1:1

10

x1
x1
x1

11

x1
x1
x1

12

M

x1
x1
x1

1:1

13

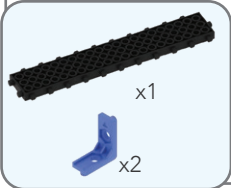
x1
x1
x1

14

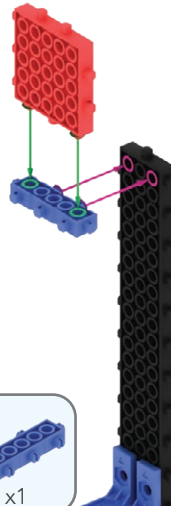
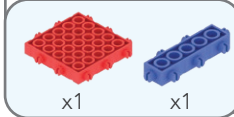
x1

15

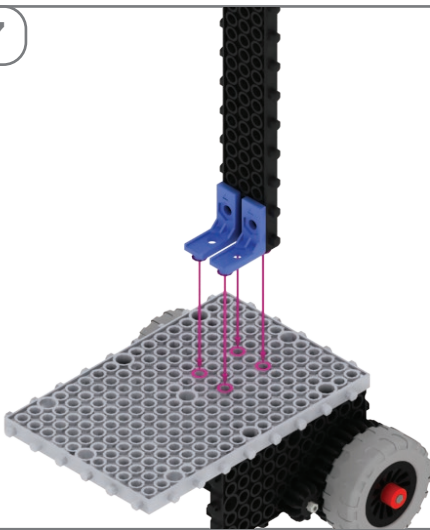
Triunghiul roșu ▲ indică poziția piese albastre L.



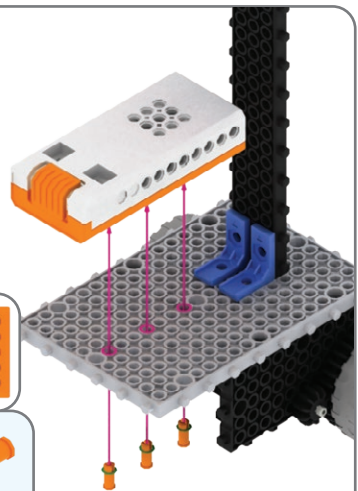
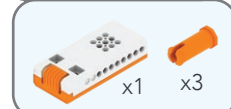
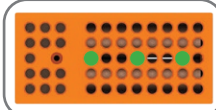
16



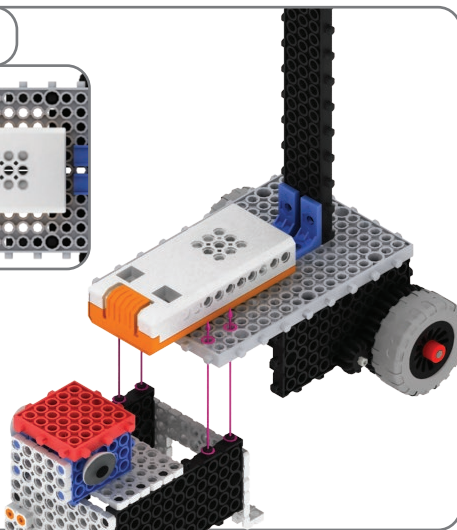
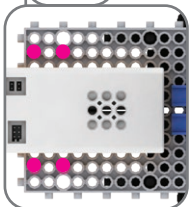
17



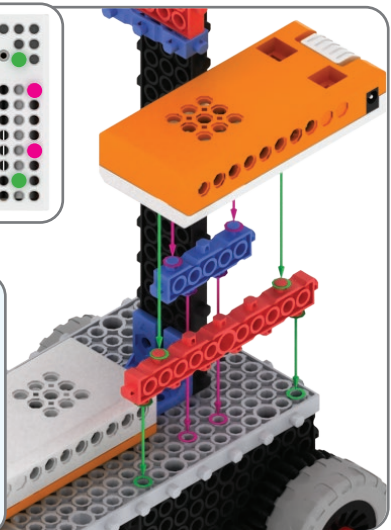
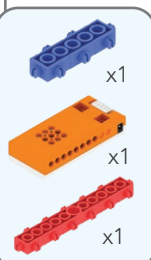
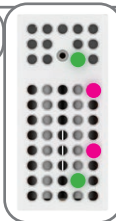
18



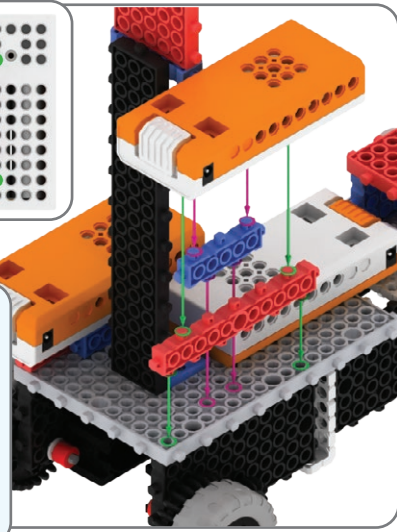
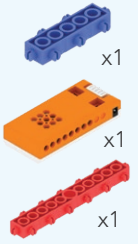
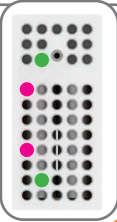
19



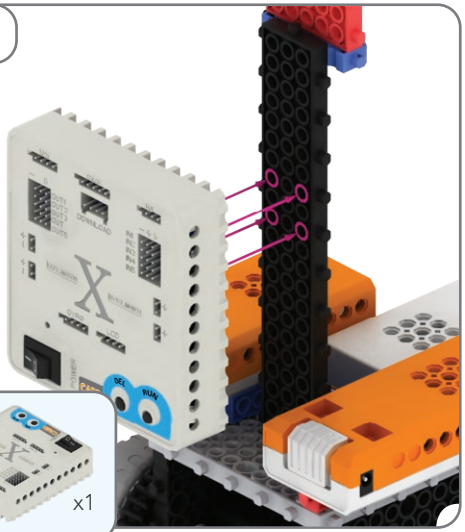
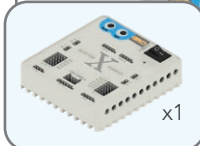
20



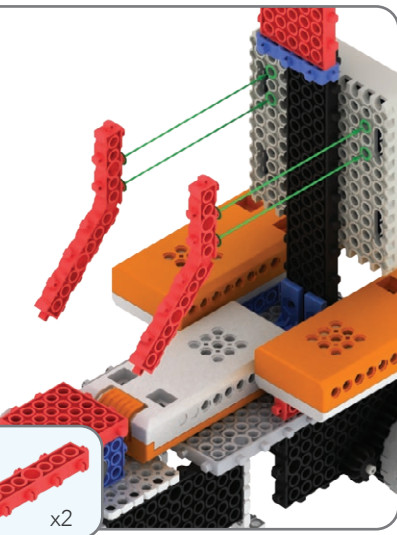
21



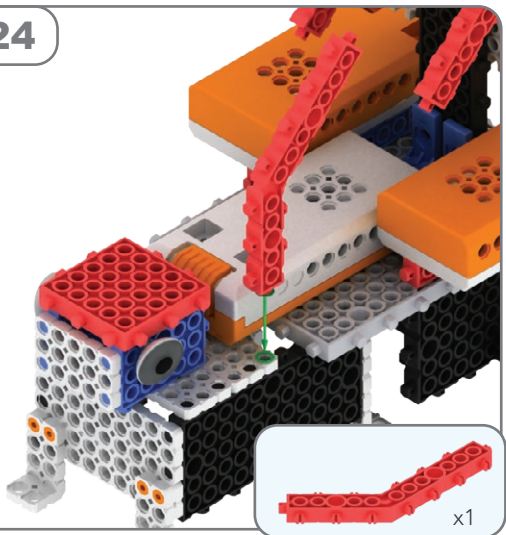
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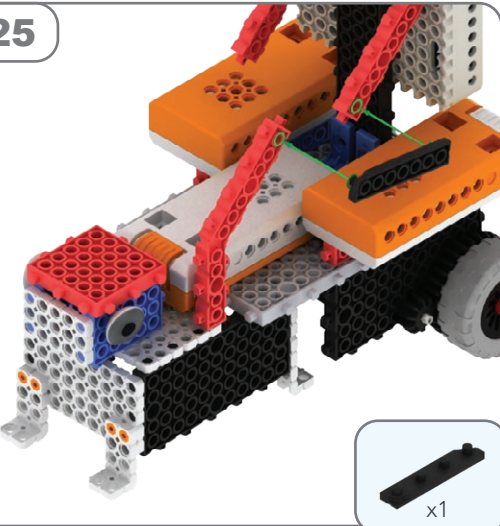
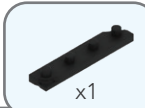
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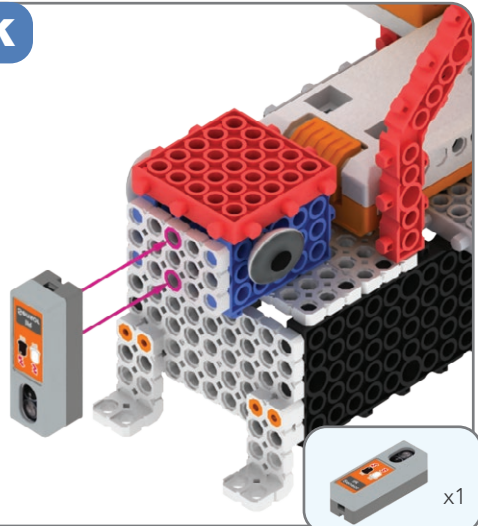
24



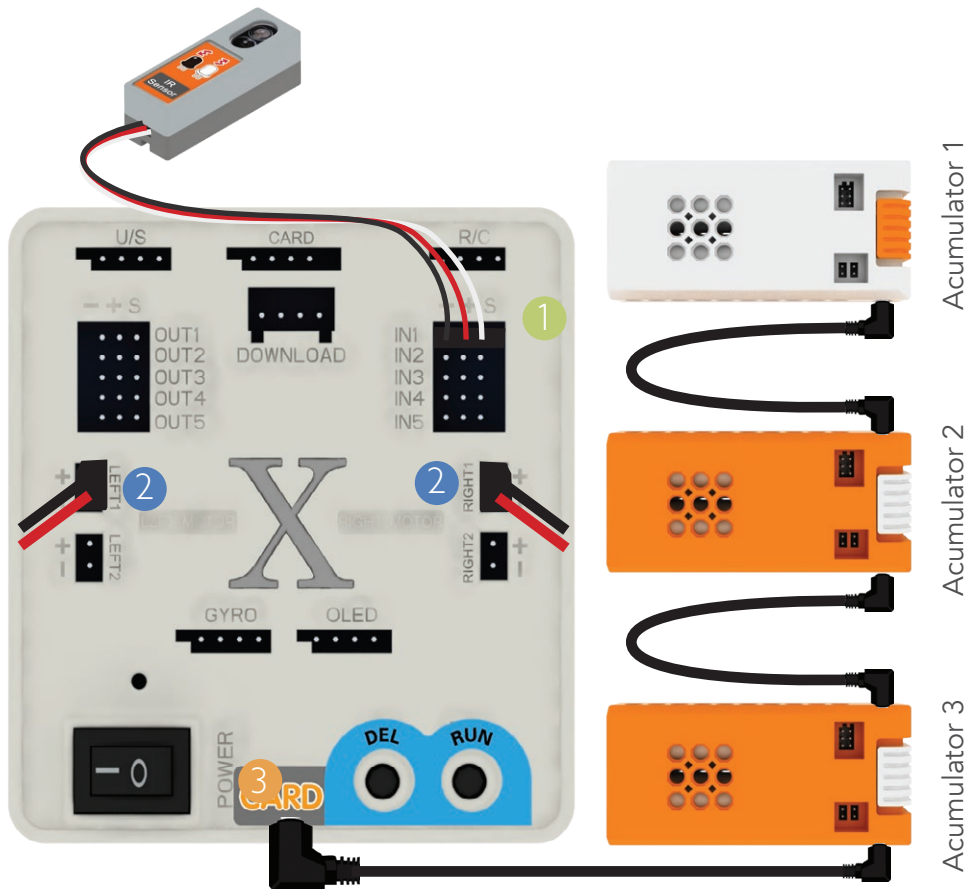
25



OK



Cum se conectează?



- 1 Conectează senzorul cu infraroșu la portul IN1.
- 2 Conectează cele două motoare la placa de bază, așa cum ți se arată în imagine.
- 3 Conectează cei trei acumulatori așa cum vezi mai sus.

Acumulatorii vor furniza energie când sunt conectați la placă prin cablul negru, indiferent de poziția întrerupătoarelor.

Cum se conectează?

Pornește placa, apoi apasă butonul RUN și apoi butonul DEL de două ori. X va clipi intermitent în albastru închis, apoi apasă RUN pentru a activa modul preprogramat 3. Robotul va merge înainte.

Când senzorul cu infraroșu detectează un obstacol, robotul virează la dreapta.

