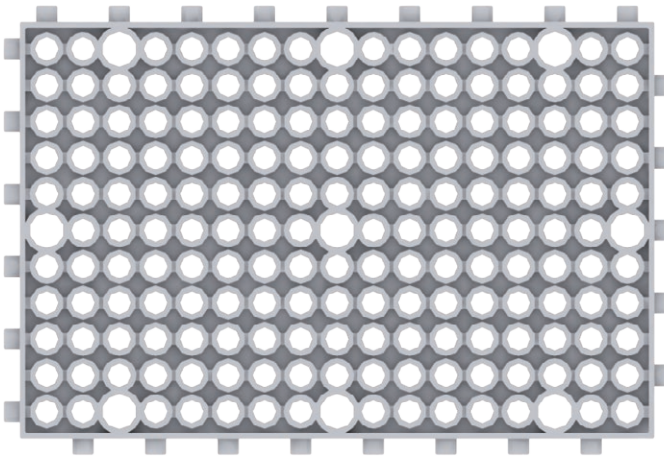




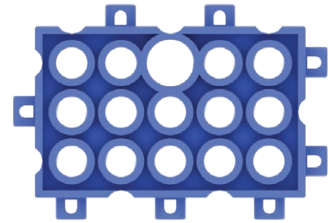
# 16 Luptător de sumo



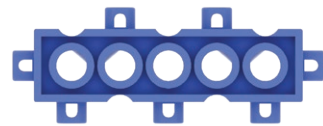
## Piese



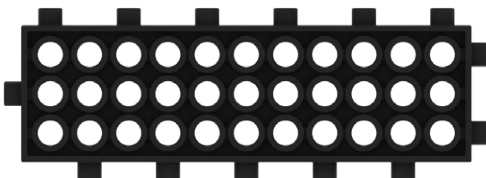
Bloc 11x17 (1)



Bloc 3x5 (3)



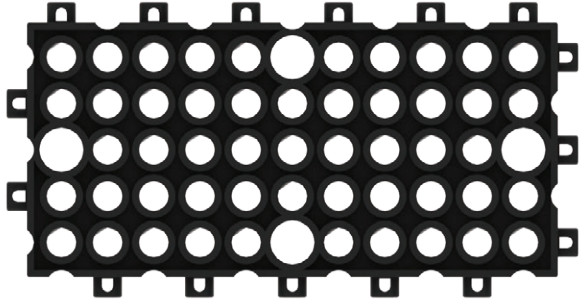
Bloc 1x5 (2)



Bloc 3x11 (2)



Bloc N 3x11 (1)



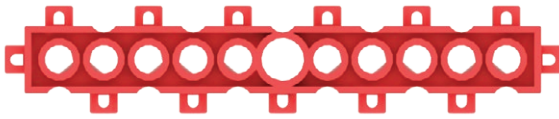
Bloc 5x11 (2)



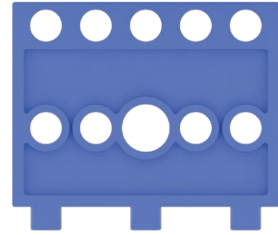
Bloc oval (2)



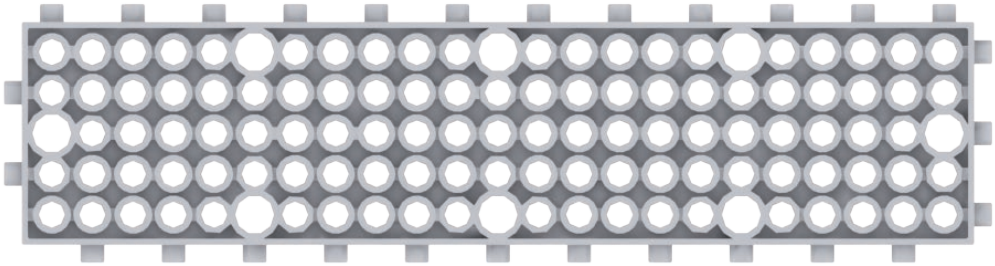
Adaptor L (6)



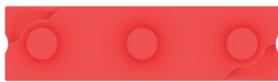
Bloc 1x11 (2)



Suport de motor (2)



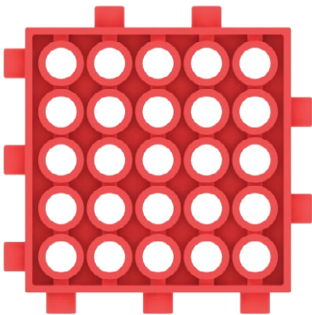
Bloc 5x23 (2)



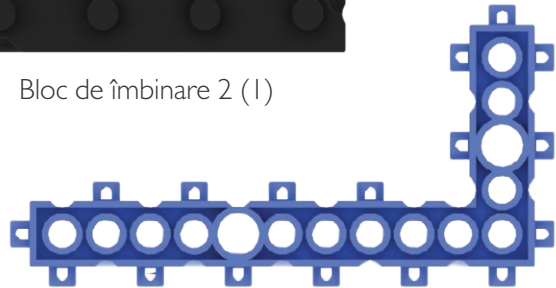
Bloc de îmbinare 1 (1)



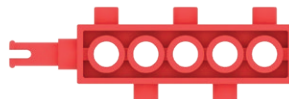
Bloc de îmbinare 2 (1)



Bloc 5x5 (3)



Bloc de 90° (4)



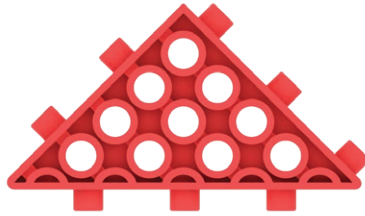
Bloc cu ax (4)



Bloc N 1x5 (1)



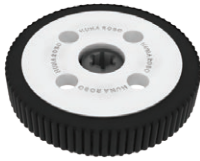
Senzor cu infraroșu (2)



Bloc triunghiular (2)



Conector de ax (2)



Roată M (2)



Motor 2 (2)



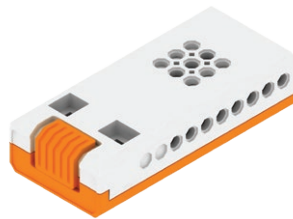
Cauciuc roșu de ax/  
Red bush (2)



Cablu de conectare (3)



Acumulator 1 (2)

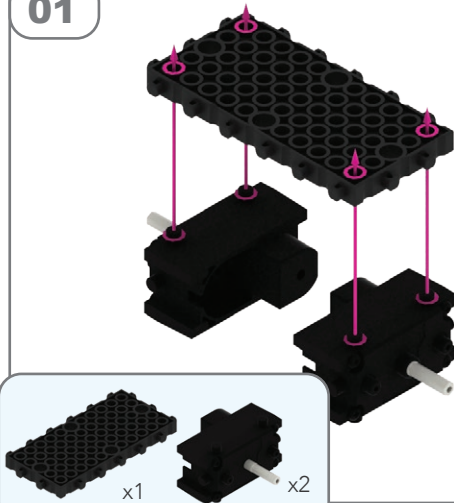


Acumulator 2 (1)

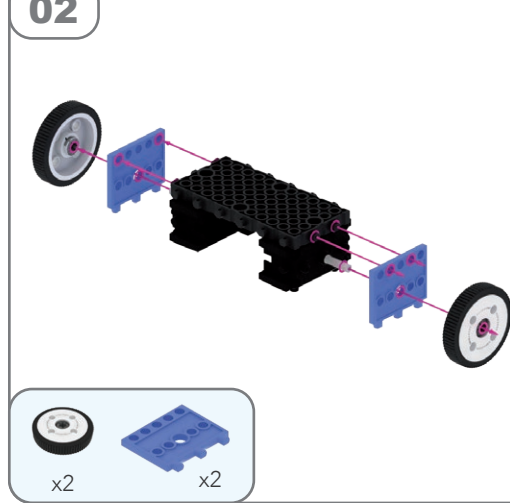


Placă de bază (1)

01



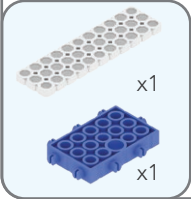
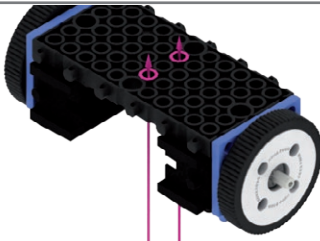
02



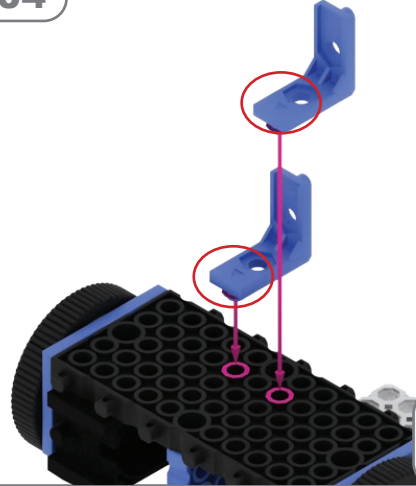


Notă: Triunghiul roșu ▲ indică poziția.

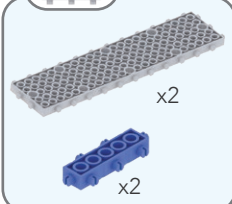
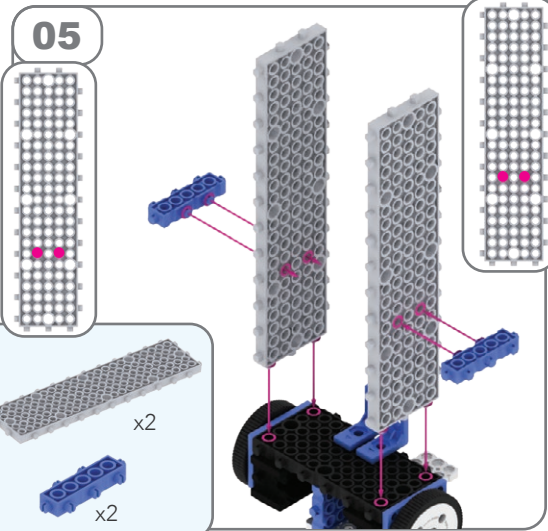
03



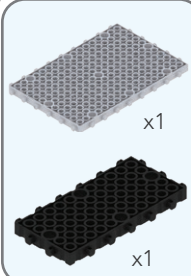
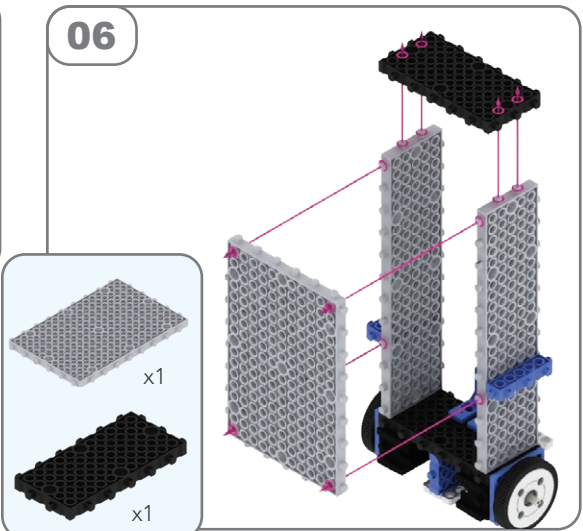
04



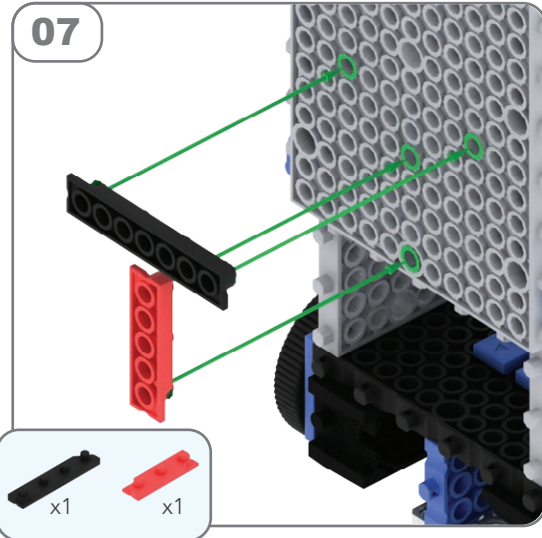
05



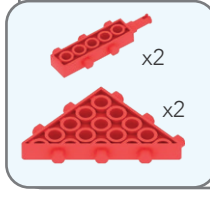
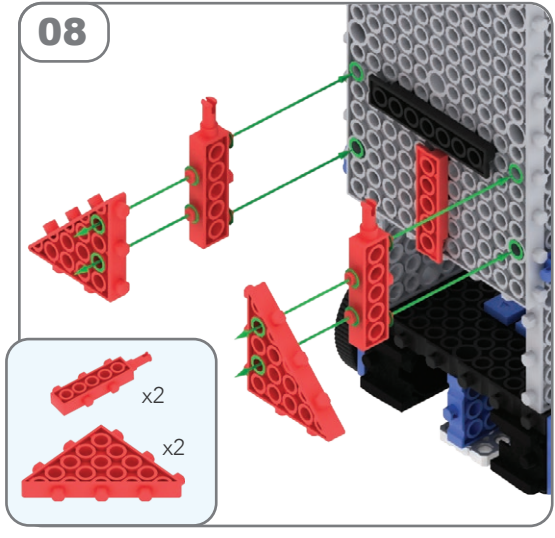
06



07

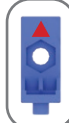
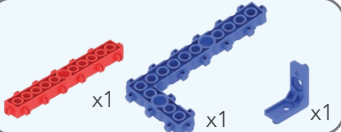
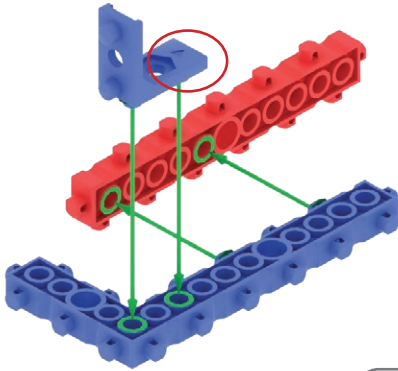


08

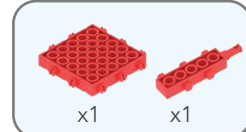
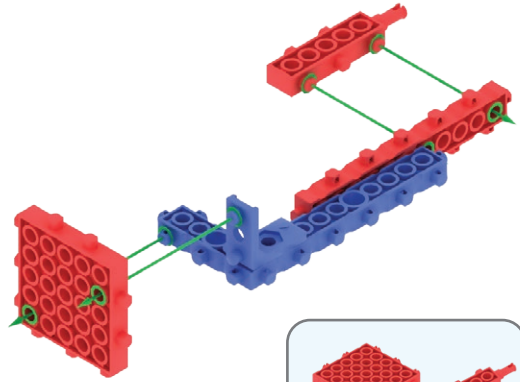


Notă: Triunghiul roșu ▲ indică poziția.

09

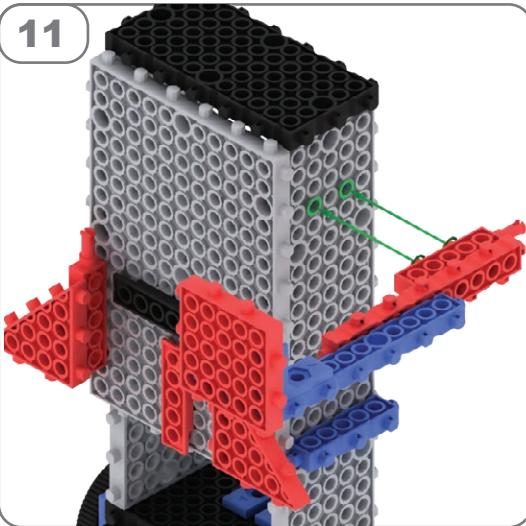


10

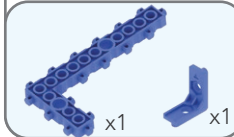
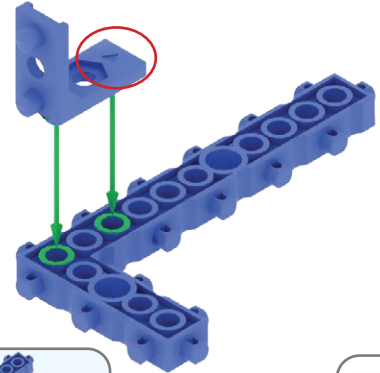


Notă: Triunghiul roșu ▲ indică poziția.

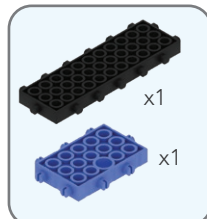
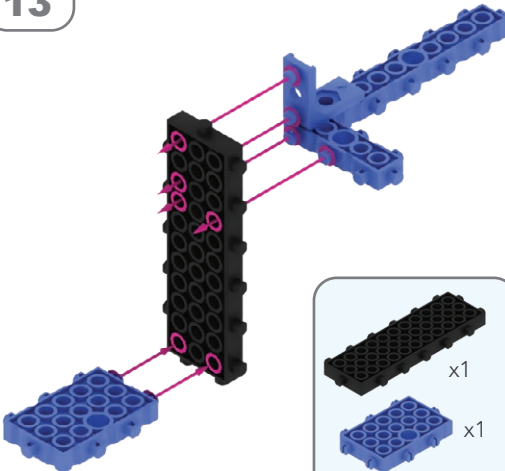
11



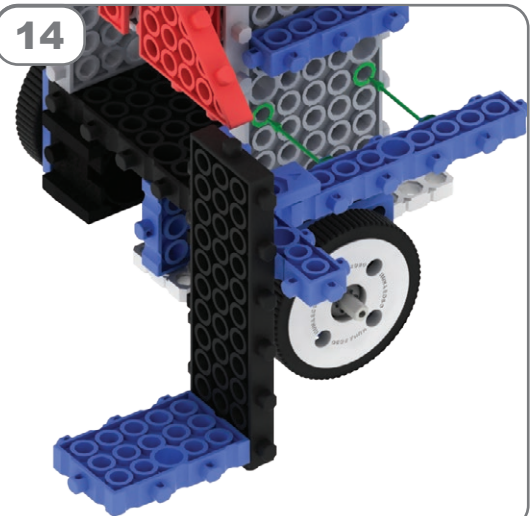
12



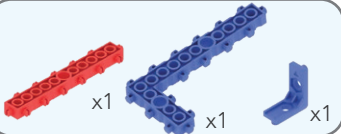
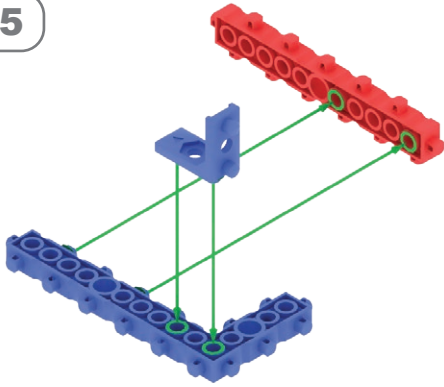
13



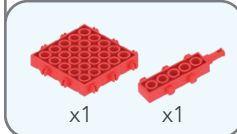
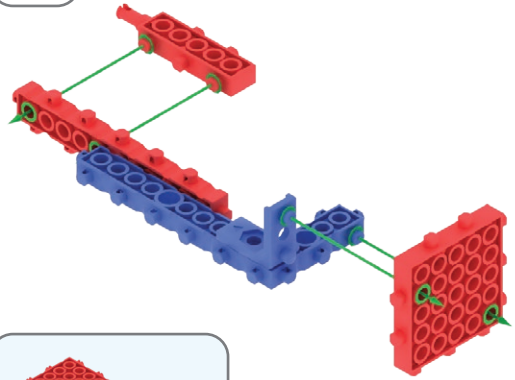
14



15

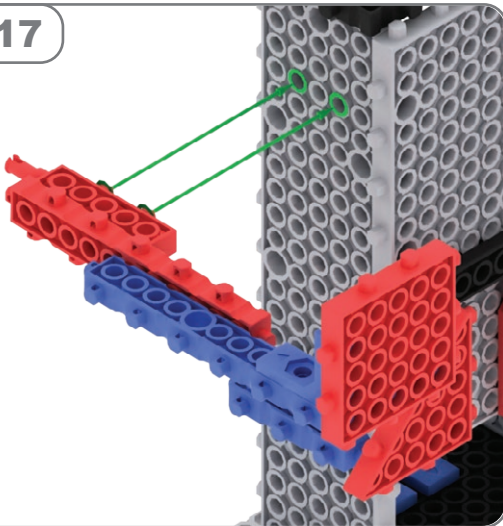


16

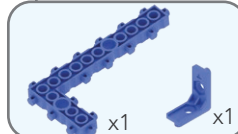
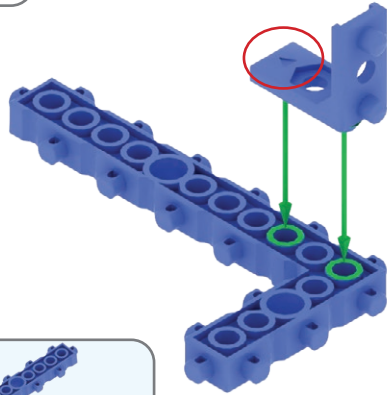


Notă: Triunghiul roșu ▲ indică poziția.

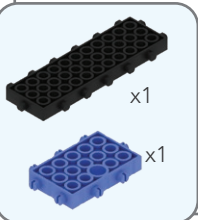
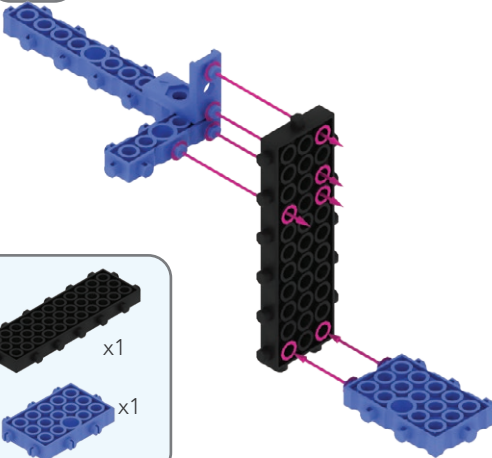
17



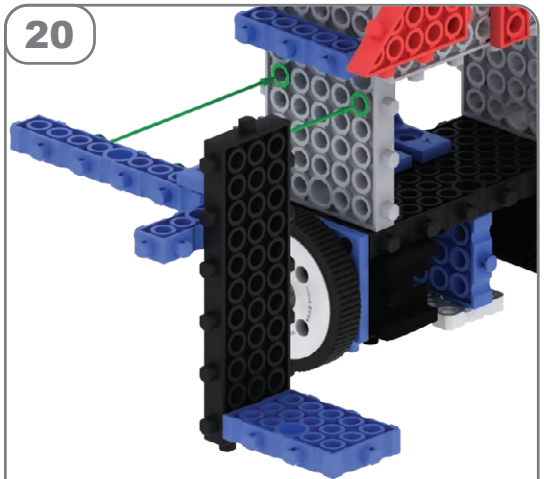
18



19

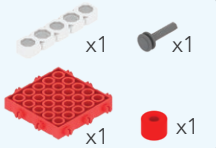
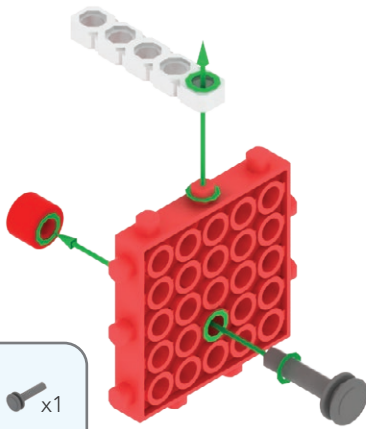


20

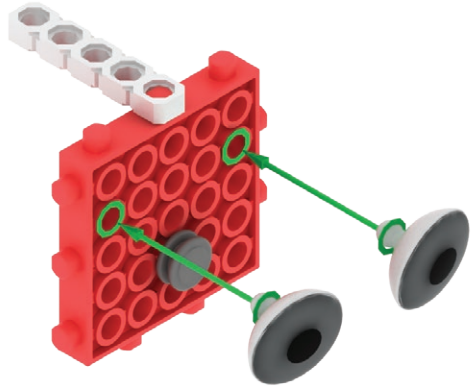




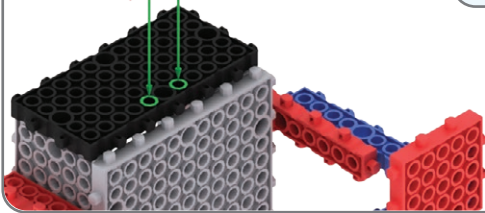
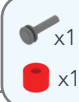
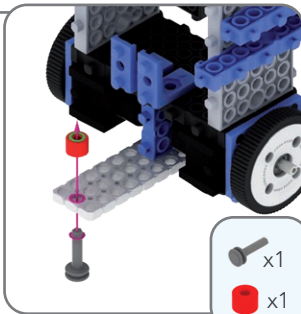
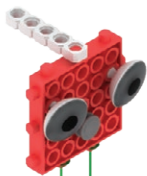
21



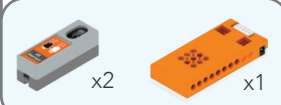
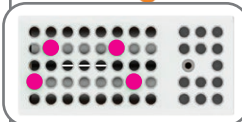
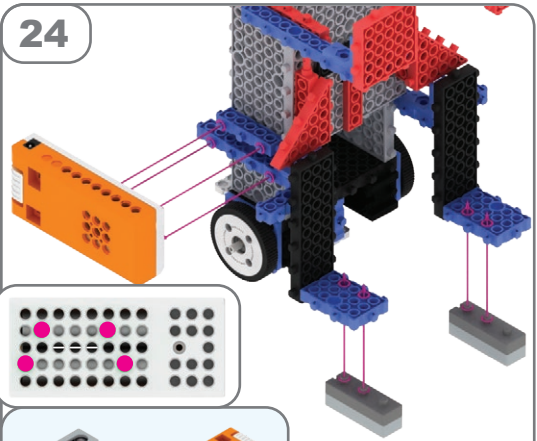
22



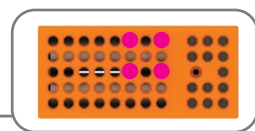
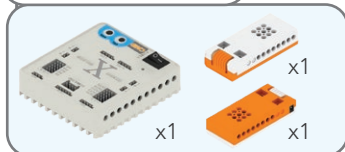
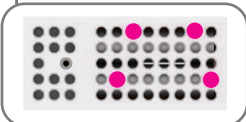
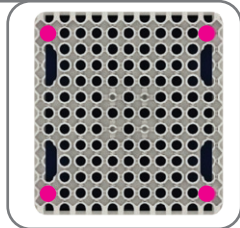
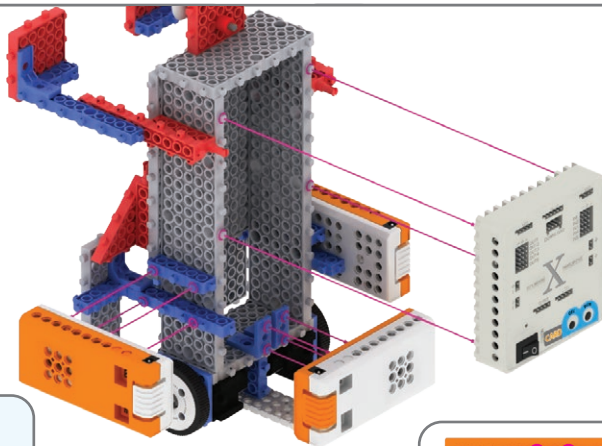
23



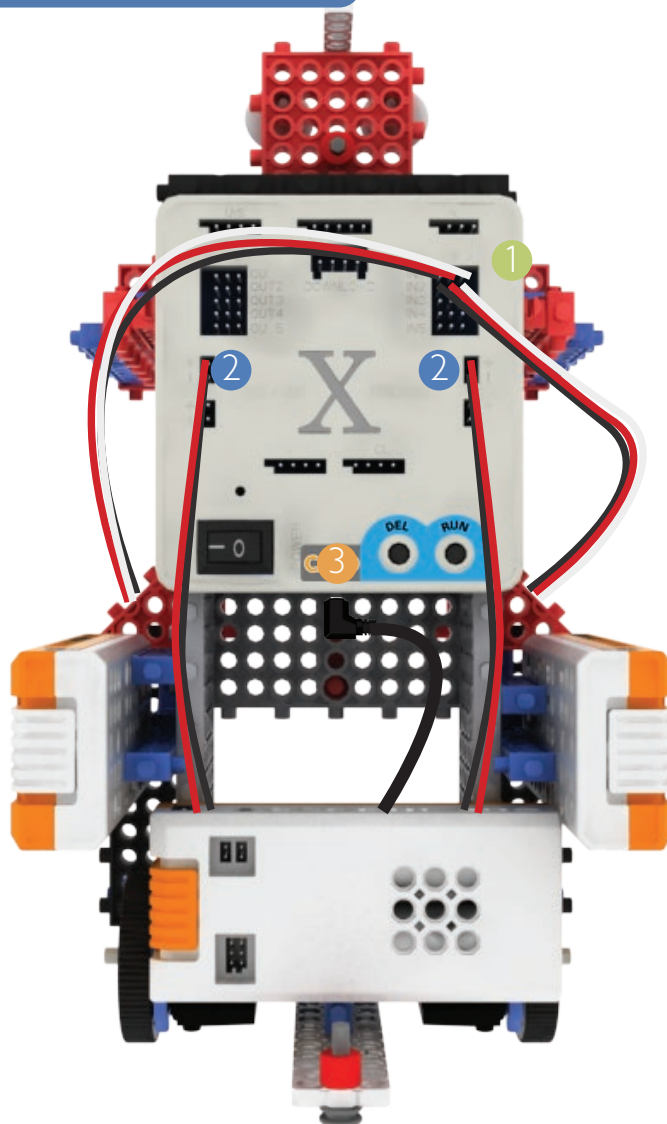
24



OK



## Cum se conectează?



- 1 Conectează senzorul cu infraroșu din stânga la portul IN1 și pe cel din dreapta la portul IN2, așa cum ți se arată mai sus.
- 2 Conectează motorul la placa de bază.
- 3 Conectează acumulatorii la placa de bază, după cum ți se arată în imagine.

Acumulatorii vor furniza energie când sunt conectați la placă prin cablul negru, indiferent de poziția întrerupătoarelor.

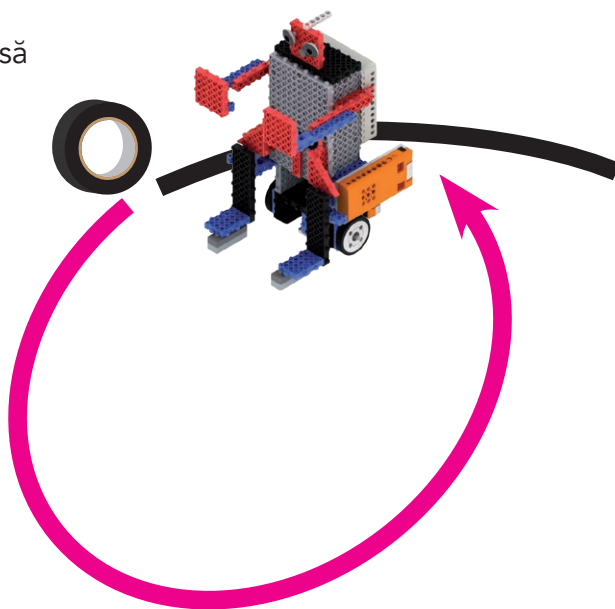


## Punere în funcțiune

Pune robotul în interiorul cercului.

Pornește placa de bază apăsând POWER, apoi apasă RUN, apoi DEL de patru ori. X va pălpi într-o culoare violet, apoi apasă RUN pentru a activa modul 5.

Robotul începe să funcționeze.



Când oricare dintre senzorii cu infraroșu detectează linia neagră, robotul se va întoarce în interiorul cercului.

