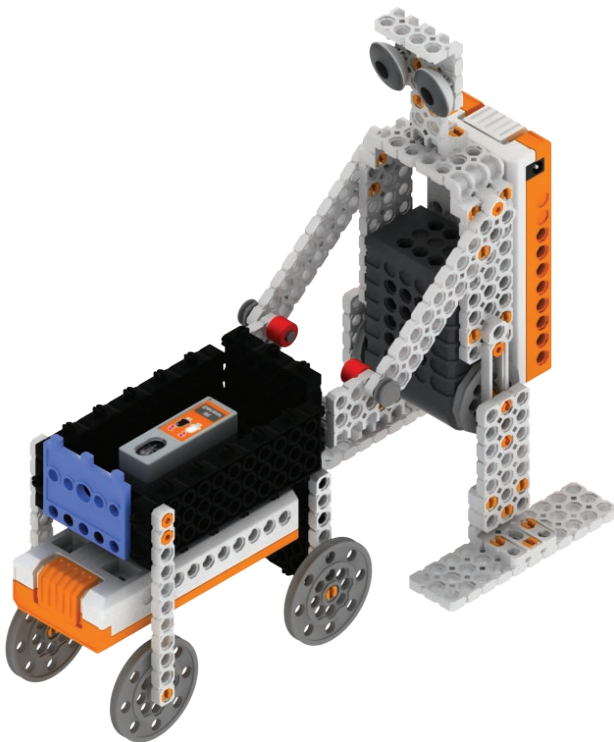




9 Coșul de cumpărături



Piese



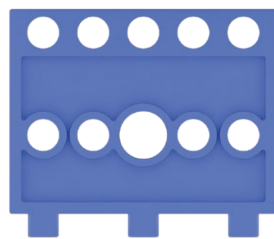
Bloc N 3×11 (2)



Bloc N 2×11 (2)



Bloc N 3×7 (2)



Suport de motor (1)



Bloc N 3×9 (2)



Bloc N 1×7 (2)



Bloc N 1×11 (2)



Adaptor L 2×3 (1)



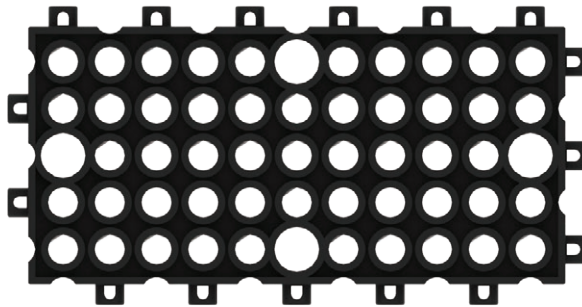
Adaptor L 2×4 (2)



Adaptor L 3×4 (4)



Adaptor L 3×3 (2)



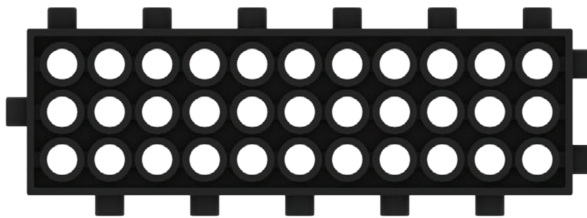
Bloc 5×11 (2)



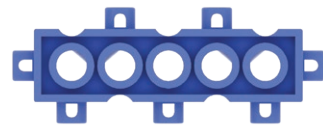
Bloc de îmbinare B1 (2)



Adaptor L (2)



Bloc 3×11 (2)



Bloc 1×5 (3)



Nit S (8)



Nit clasic (34)



Nit L (4)



Jantă/Hub 1 (4)



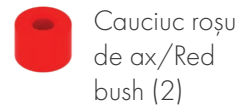
Nit dublu de tip 1 (2)



Bloc oval (2)



Conector de ax (2)



Cauciuc roșu de ax/Red bush (2)



Senzor cu infraroșu (1)



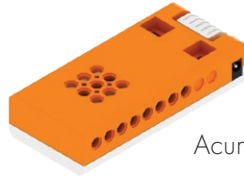
Motor 1 (1)



Acumulator 1 (1)

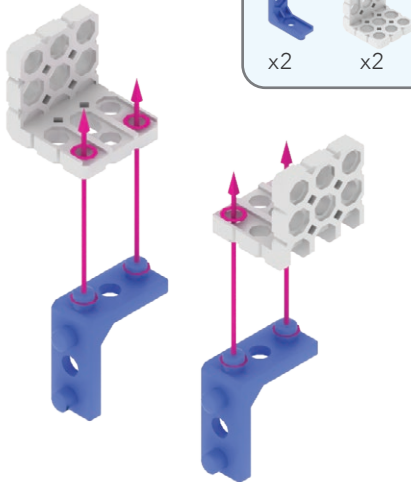


Cablu de conectare (1)

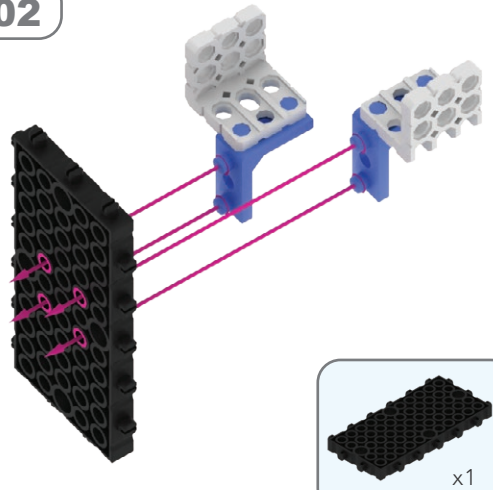


Acumulator 2 (1)

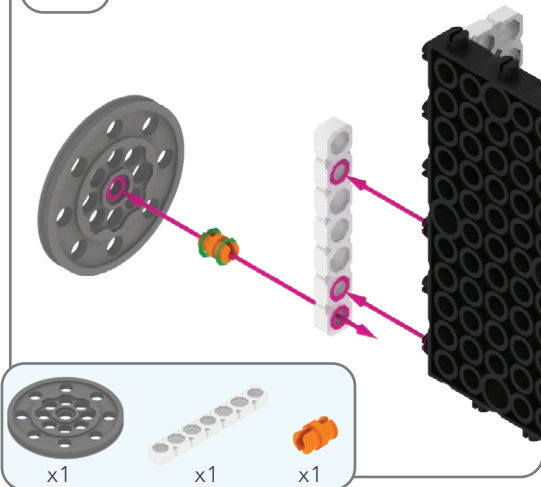
01



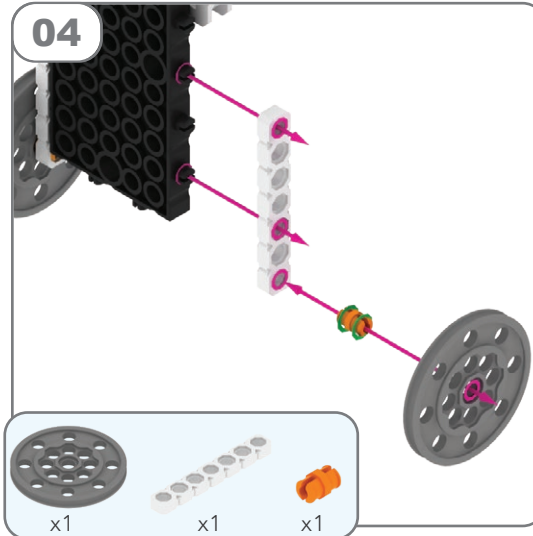
02



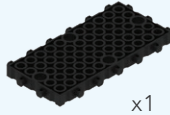
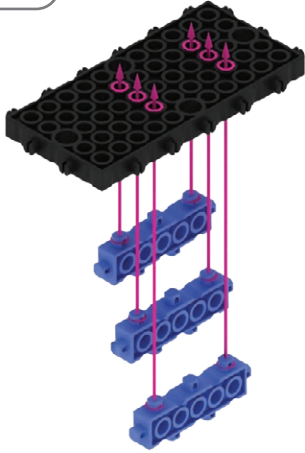
03



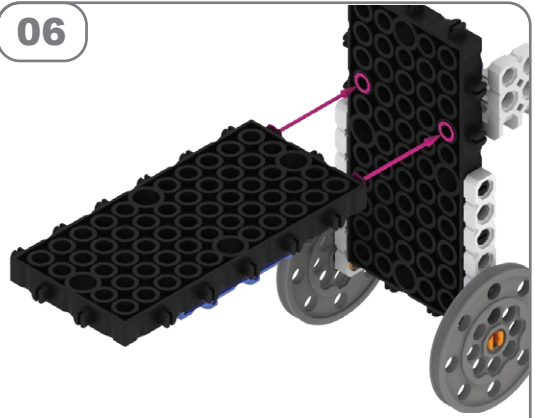
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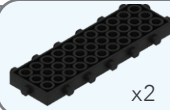
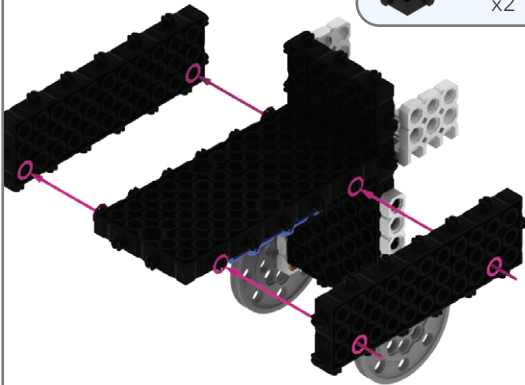
05



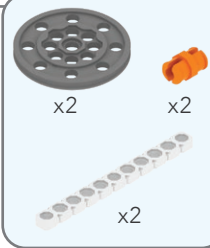
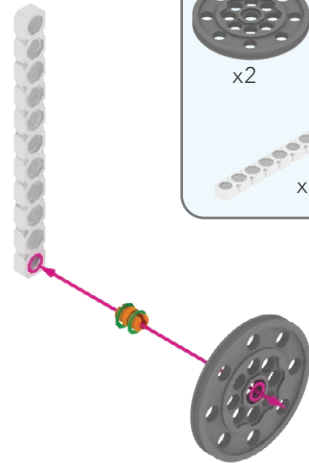
06



07

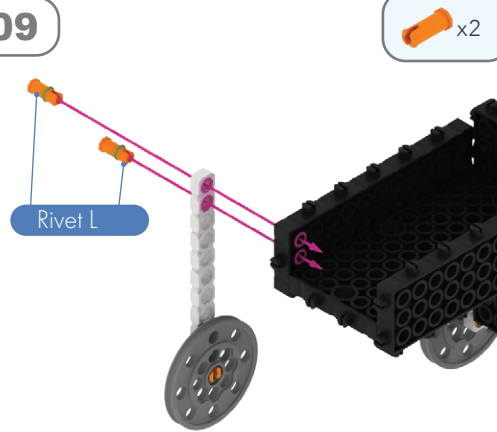


08

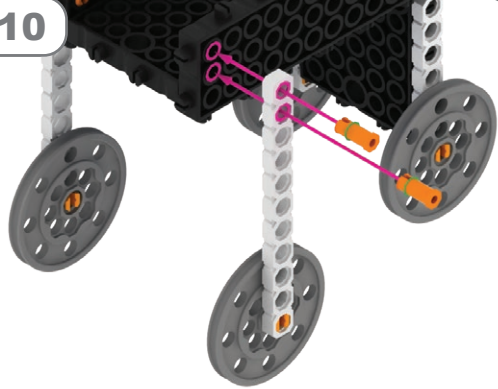


X2

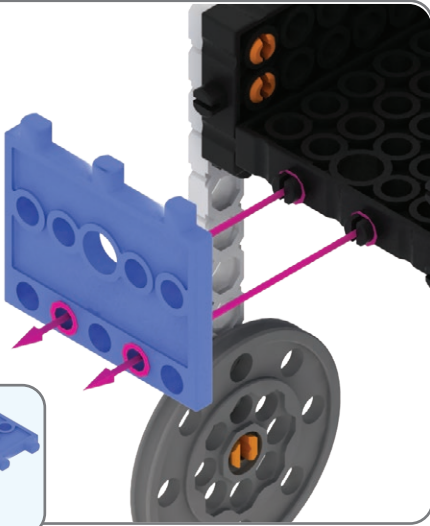
09



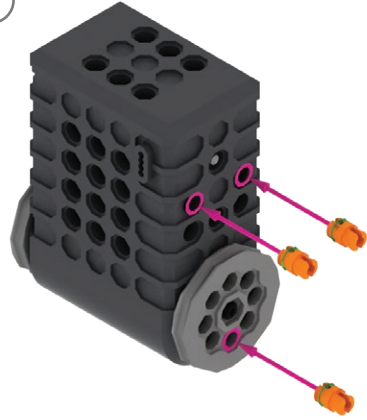
10



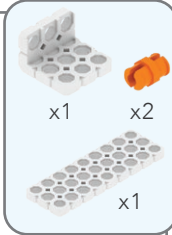
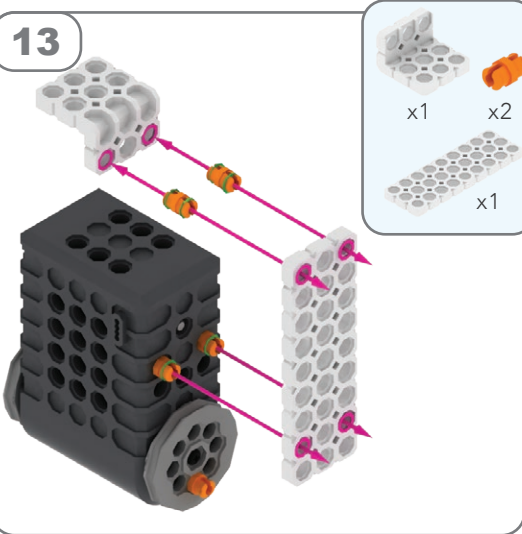
11



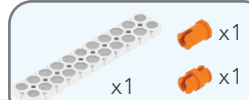
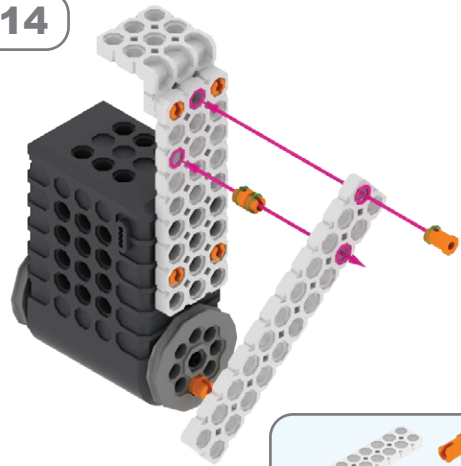
12



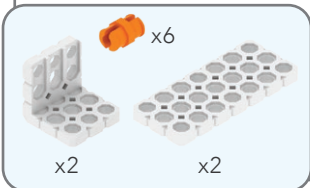
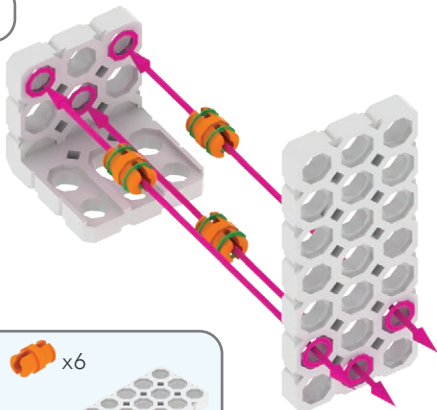
13



14

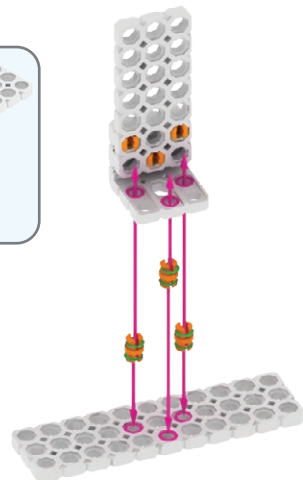
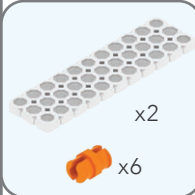


15



X2

16



X2

17

x1 x3

18

x3

19

x1 x2

x1 x1

20

x1 x1

x1 x1

21

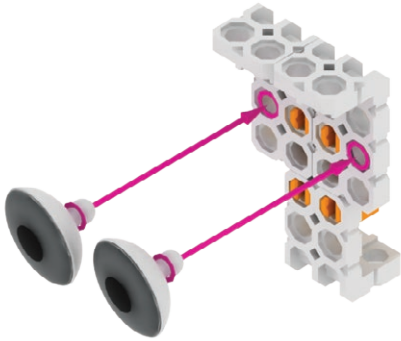
16

x1 x3

22

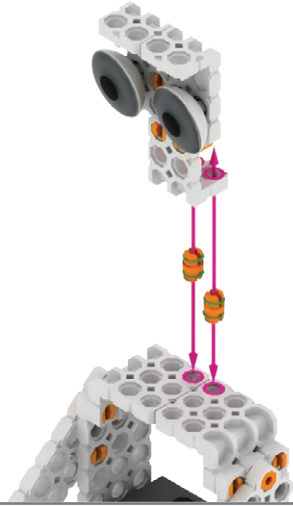
x1 x2 x2

23

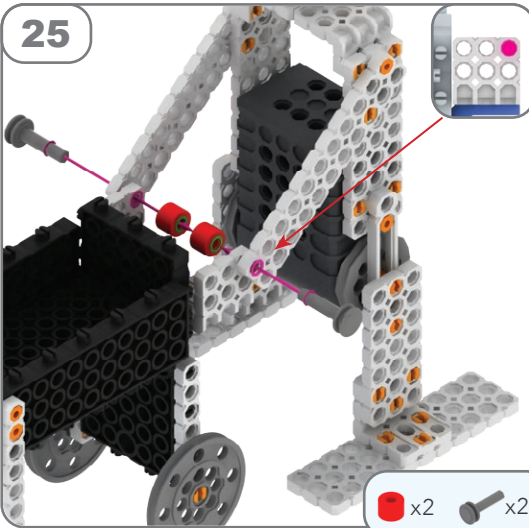


24

 x2

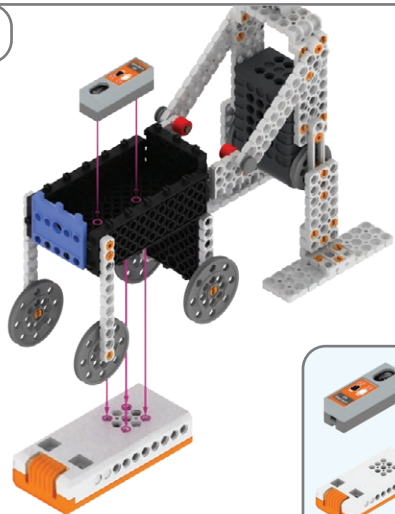




25



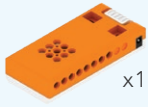

 x2  x2

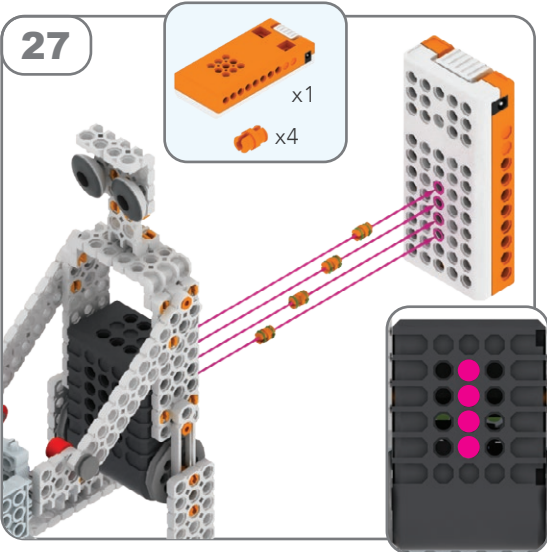
26



 x1
 x1

27

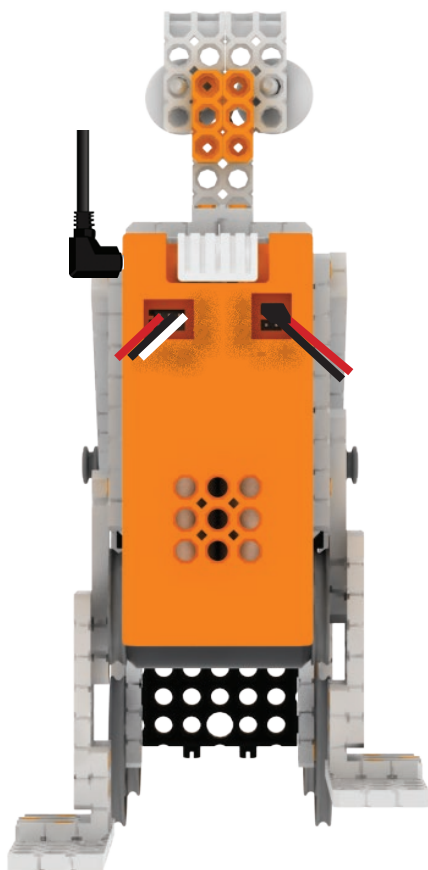
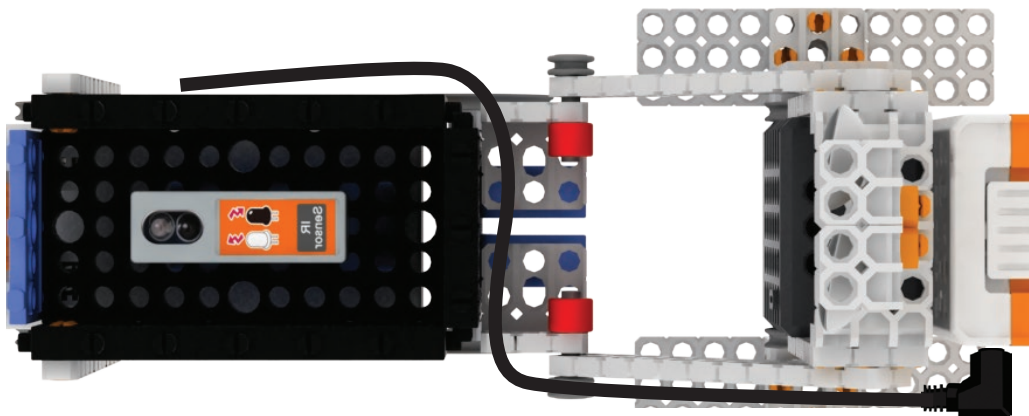
 x1
 x4



OK



Cum se conectează?



Senzorul cu infraroșu se conectează la acumulator astfel: cablul negru la „-”, cablul roșu la „+” și cablul alb la „S”.

Roșul cablului motorului se conectează la + și negru la -, ceea ce va face robotul nostru să se pună în mișcare.

IMPORTANT: Când nu utilizezi robotul, deconectează senzorul cu infraroșu pentru ca bateriile să nu se descarce.