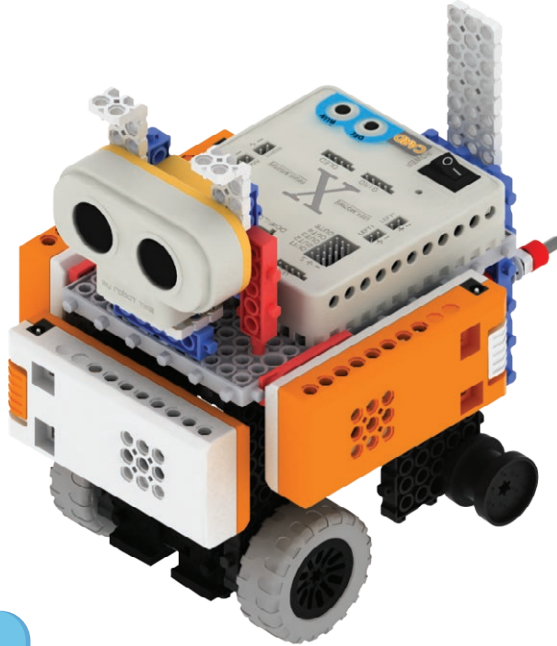
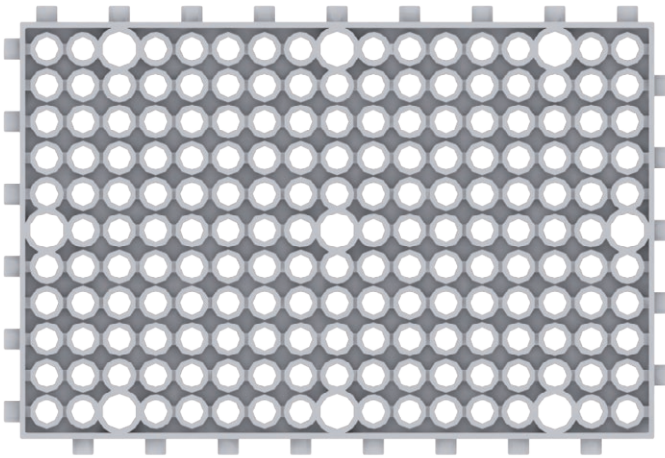




33 Robot câine



Piese



Bloc 11x17 (1)



Adaptor L 2x4 (2)



Bloc N 1x7 (1)



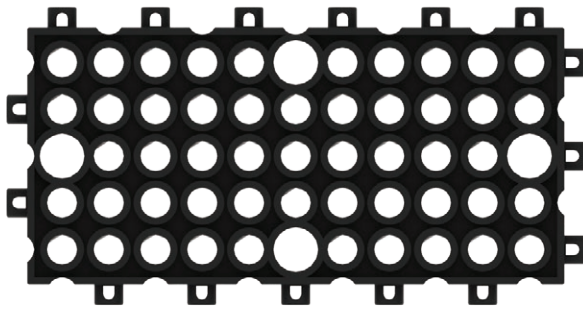
Bloc N 3x9 (3)



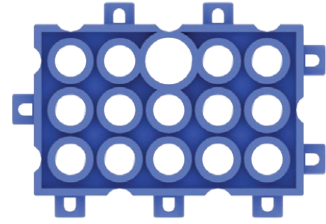
Bloc N 3x5 (1)



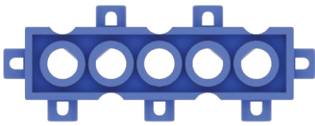
Bloc N 1x5 (1)



Bloc 5x11 (4)



Bloc 3x5 (1)



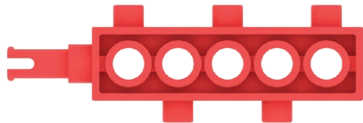
Bloc 1x5 (6)



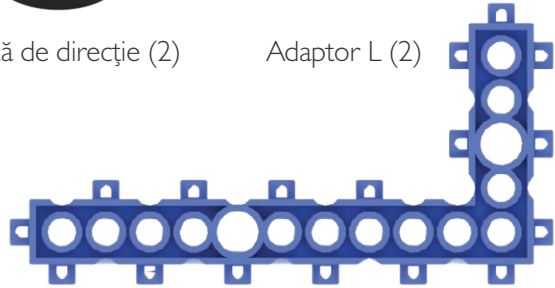
Roată de direcție (2)



Adaptor L (2)



Bloc cu ax (2)



Bloc de 90° (1)



Roată M (2)



Jantă 2 (1)



Motor 2 (2)



Conector de ax (2)



Cauciuc roșu de ax (2)



Piuliță (4)



Ax S (1)



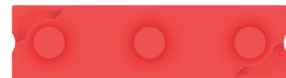
Nit clasic (7)



Nit S (1)



Nit L (3)



Bloc de îmbinare 1 (2)



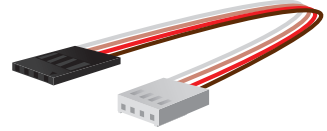
Motor 1 (1)



Senzor de ultrasunete (1)



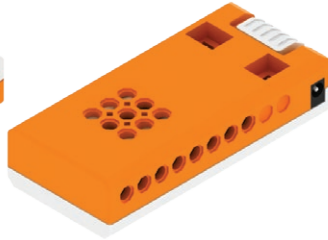
Cablu de conectare (3)



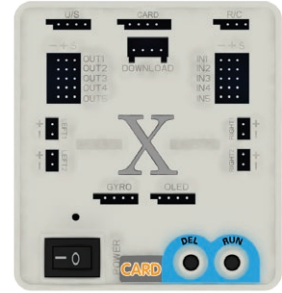
Prelungitor (1)



Acumulator 1 (1)

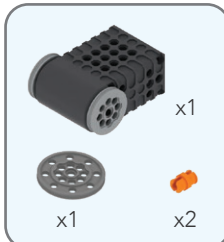
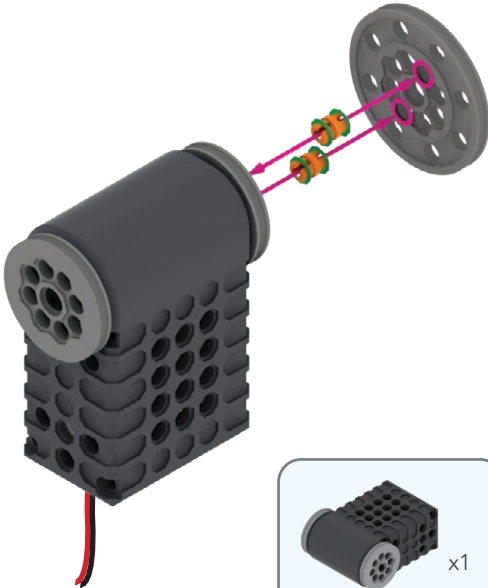


Acumulator 2 (2)

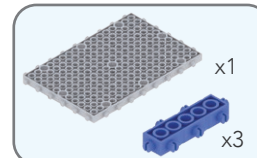
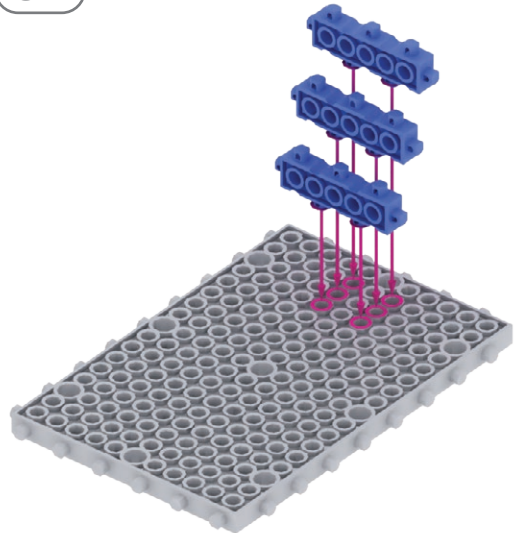


Placă de bază MRT Card(1)

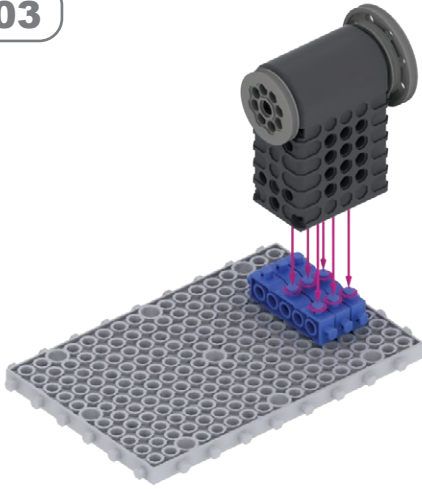
01



02

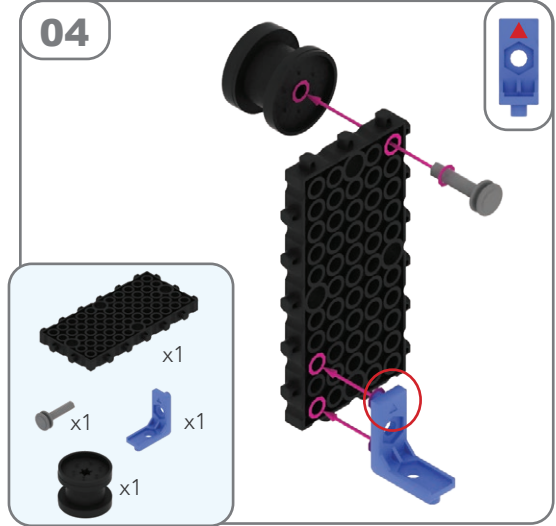


03



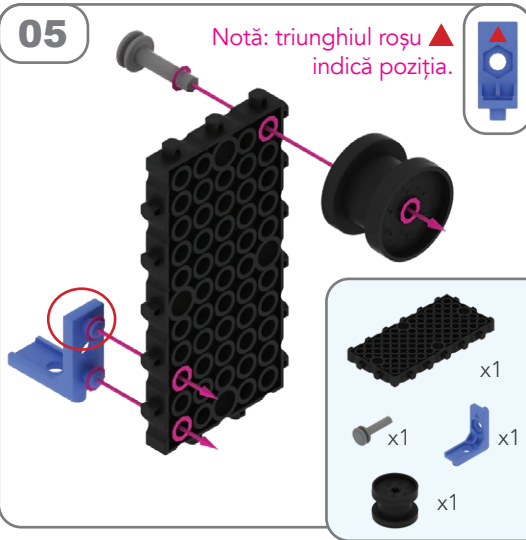
04

Notă: triunghiul roșu ▲ indică poziția.

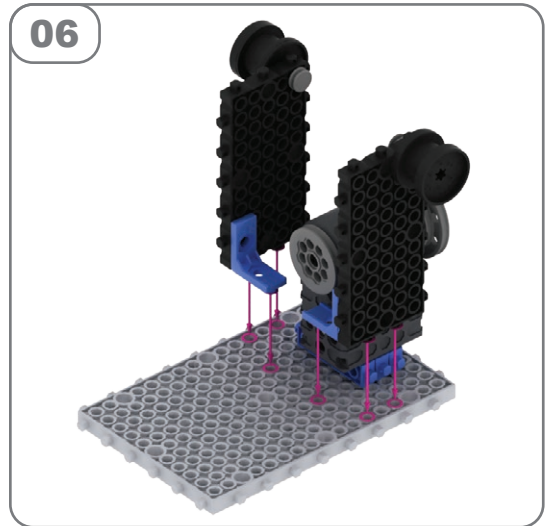


05

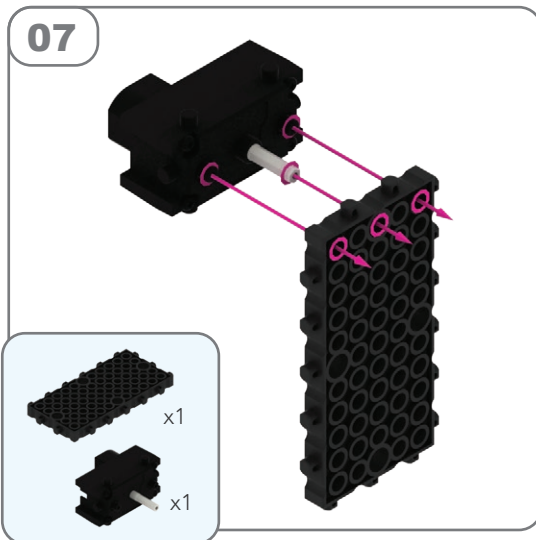
Notă: triunghiul roșu ▲ indică poziția.



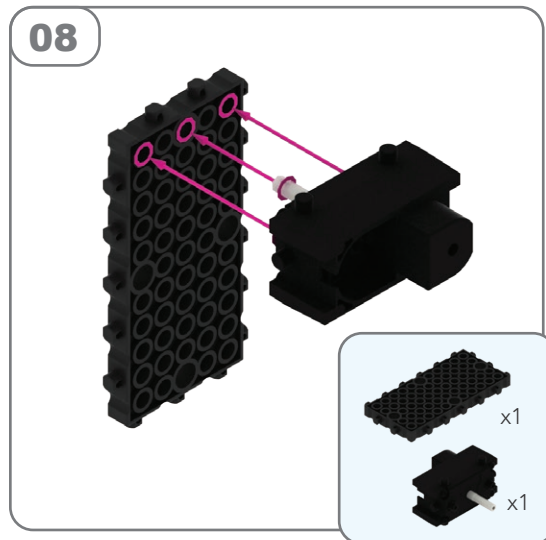
06



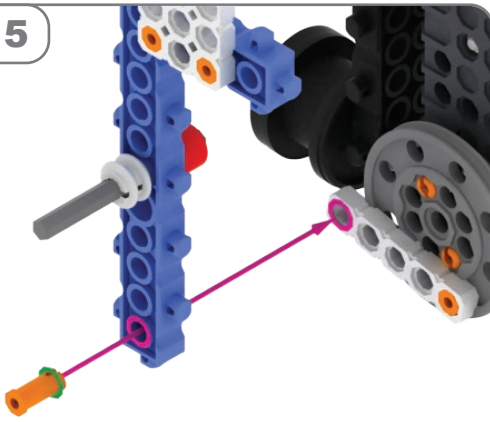
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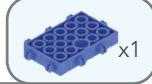
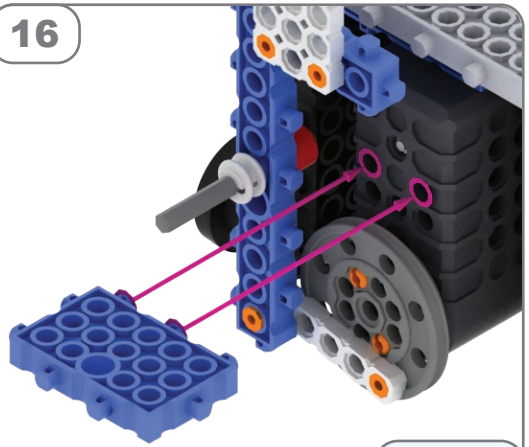
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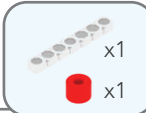
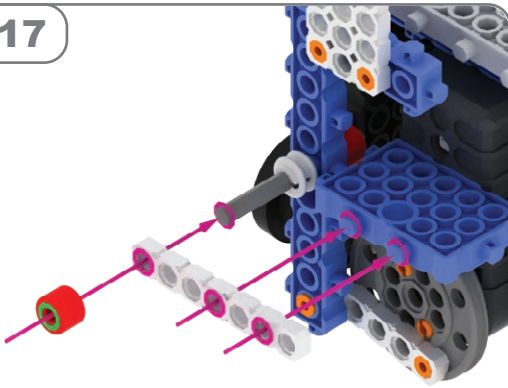
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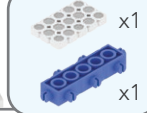
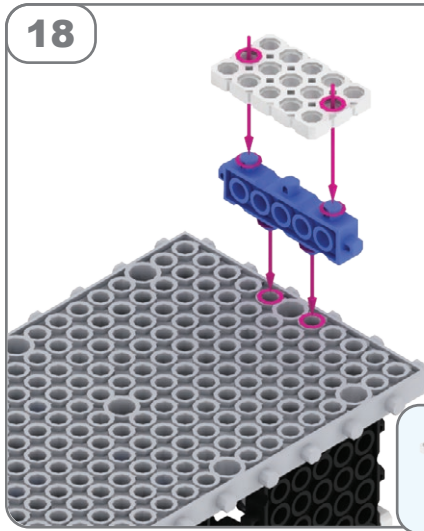
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17



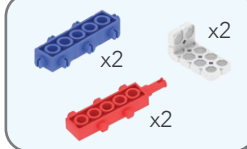
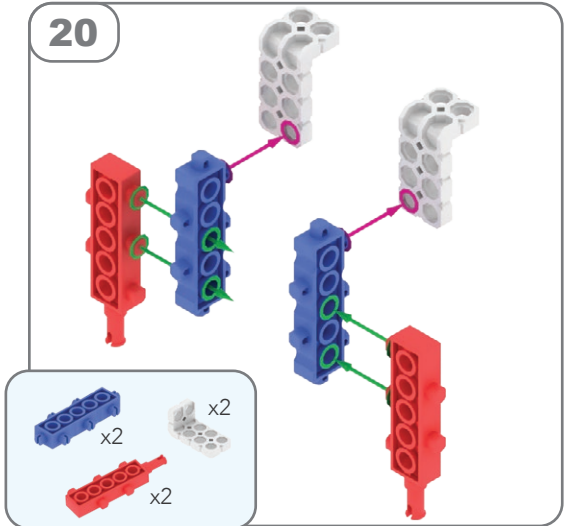
18

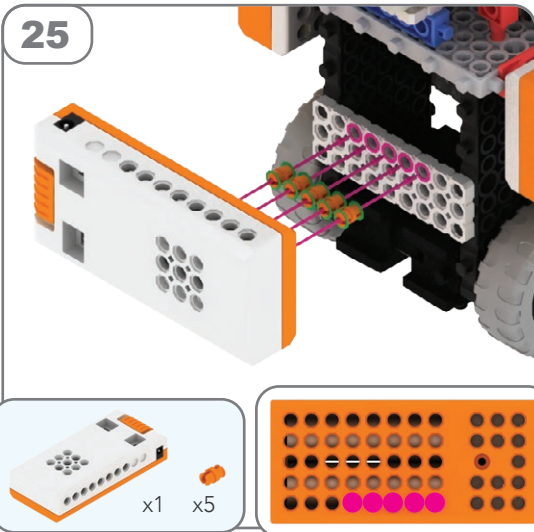
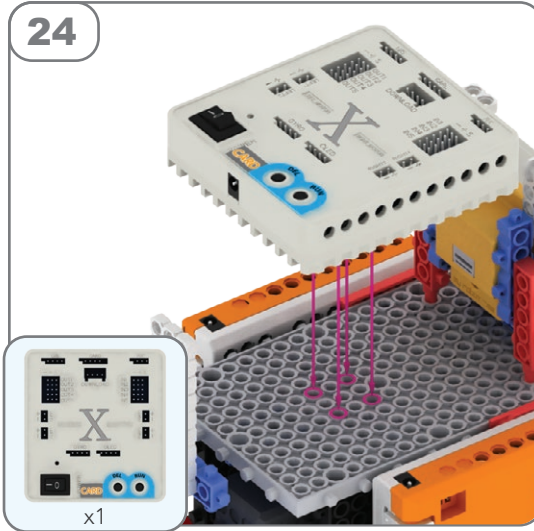
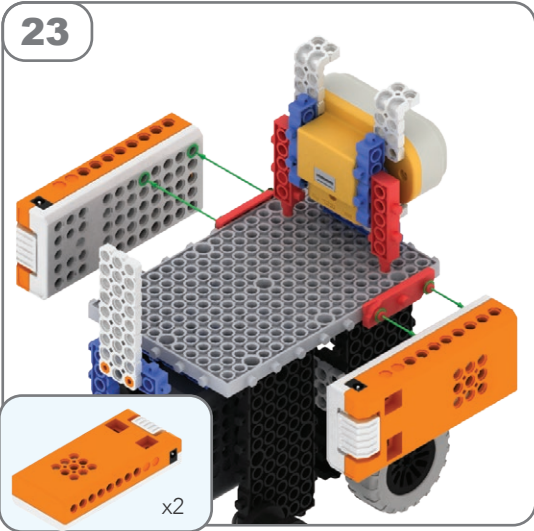
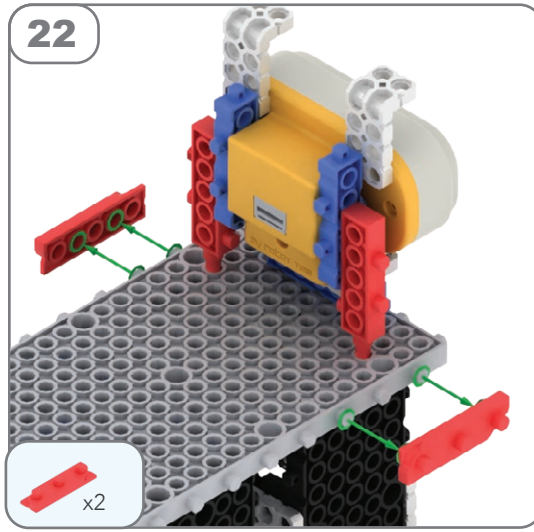
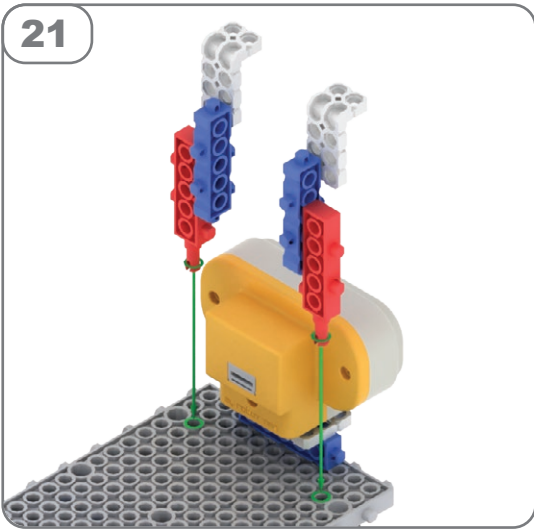


19

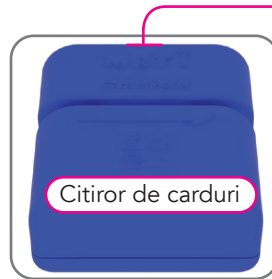


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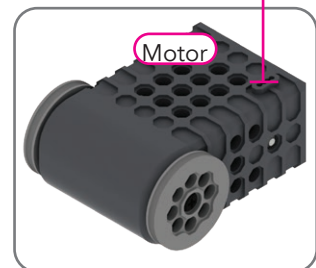
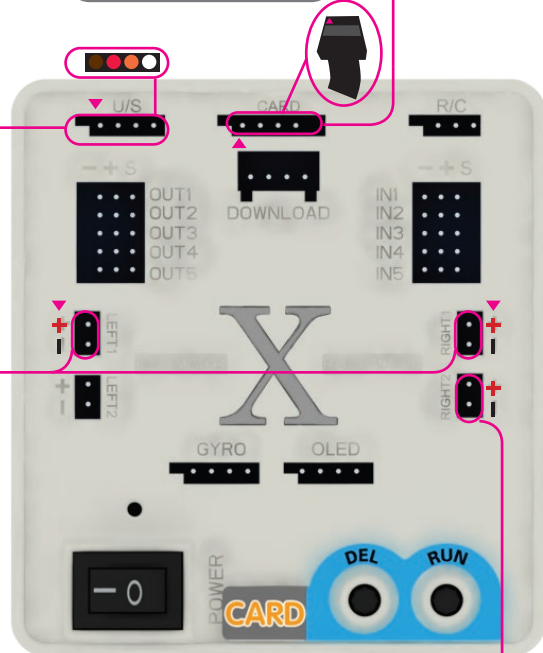
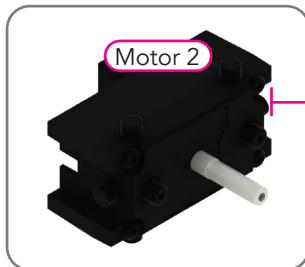




Cum se conectează?



Triunghiul ▲ trebuie să corespundă cu ▲ de pe conectorul cablului de pe cititorul de carduri



În practică



Detect distance
2cm-10cm



Detect distance
10cm-50cm



Delay 1 sec



Detect distance
50cm-100cm



Stop



Forward



Right motor 2
counterclockwise rotation



Cycle start
(all time)



Cycle end

Programare:

1. Cycle start (all time)
2. Detect distance 50cm-100cm
3. Stop
4. Detect distance 10cm-50cm
5. Forward
6. Delay 1 sec
7. Stop
8. Detect distance 2cm-10cm
9. Right motor 2 counterclockwise rotation
10. Cycle end